

ANALISI MATEMATICA

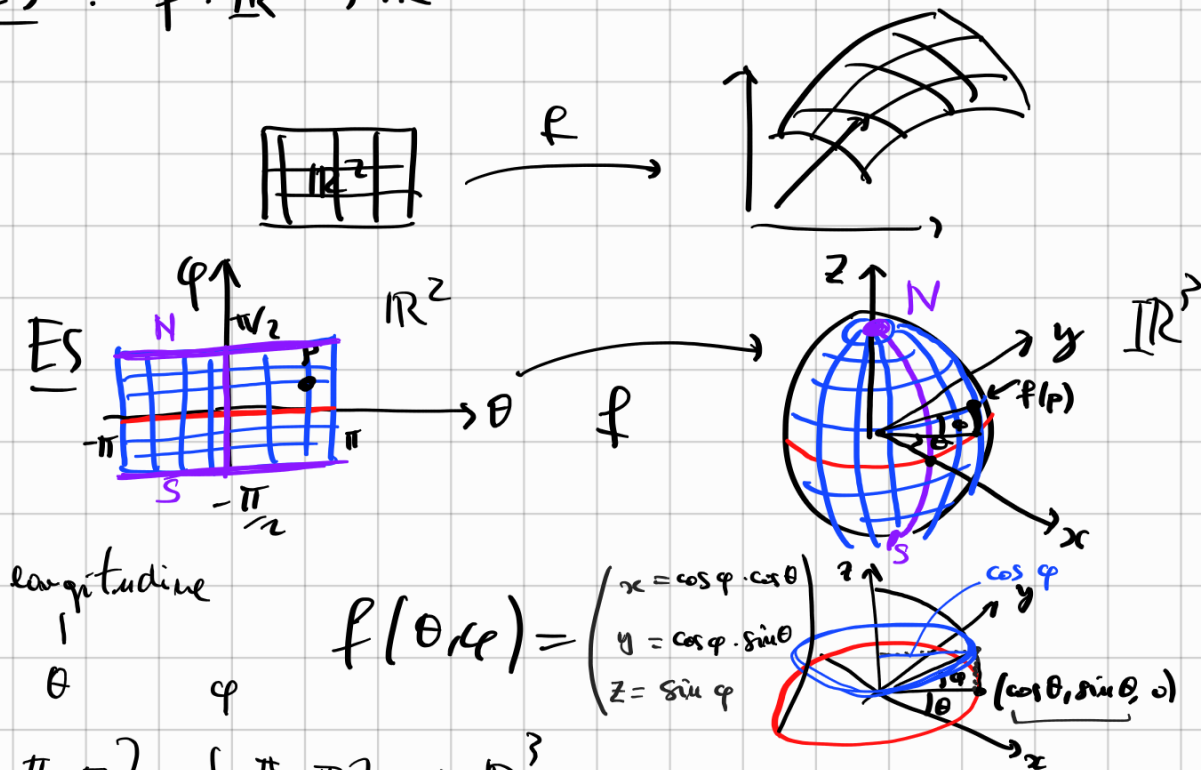
17.3.2023

$$f: \mathbb{R}^n \rightarrow \mathbb{R}^m$$

$$f: \mathbb{R}^n \rightarrow \mathbb{R} \quad m=1$$

$$f: \mathbb{R} \rightarrow \mathbb{R}^m \quad m=1$$

ES: $f: \mathbb{R}^2 \rightarrow \mathbb{R}^3$



longitudine
|
 θ

latitudine
|
 φ

$$f(\theta, \varphi) = \begin{pmatrix} x = \cos \varphi \cdot \cos \theta \\ y = \cos \varphi \cdot \sin \theta \\ z = \sin \varphi \end{pmatrix}$$

$$f: [-\pi, \pi] \times [-\frac{\pi}{2}, \frac{\pi}{2}] \rightarrow \mathbb{R}^3$$

Formula di Taylor al I ordine:

se $f: \Omega \subseteq \mathbb{R}^n \rightarrow \mathbb{R}^m$ è di classe C^1 :

$$\underline{y} = f(\underline{x}) = \underbrace{f(\underline{x}_0)}_{\mathbb{R}^m} + \underbrace{Df(\underline{x}_0)}_{\mathbb{R}^{m \times n}} \cdot \underbrace{(\underline{x} - \underline{x}_0)}_{\mathbb{R}^n} + o(|\underline{x} - \underline{x}_0|)$$

per $\underline{x} \rightarrow \underline{x}_0$

$$Df(\underline{x}_0) = \begin{pmatrix} \frac{\partial f_j}{\partial x_k} \end{pmatrix}_{m \times n}$$

$$k = 1 \dots n$$

$$j = 1 \dots m$$

$$\underline{f}(\underline{x}) = \begin{pmatrix} f_1(\underline{x}) \\ \vdots \\ f_m(\underline{x}) \end{pmatrix}$$

MATRICE JACOBIANA

$$Df(\underline{x}_0) = \begin{pmatrix} Df_1 \\ Df_2 \\ \vdots \\ Df_m \end{pmatrix} \begin{matrix} \uparrow \\ m \\ \downarrow \end{matrix}$$

$$\leftarrow \begin{matrix} m \\ \leftarrow \end{matrix}$$

$$Df_1 = (\nabla f_1)^t$$

$$\nabla f_1 = \begin{pmatrix} \frac{\partial f_1}{\partial x_1} \\ \vdots \\ \frac{\partial f_1}{\partial x_n} \end{pmatrix}$$

Es $f(\theta, \varphi) = \begin{pmatrix} \cos \varphi \cdot \cos \theta \\ \cos \varphi \cdot \sin \theta \\ \sin \varphi \end{pmatrix} = \begin{pmatrix} f_1 \\ f_2 \\ f_3 \end{pmatrix}$ 3 righe

$$Df(\theta, \varphi) = \begin{pmatrix} \frac{\partial f_1}{\partial \theta} & \frac{\partial f_1}{\partial \varphi} \\ \frac{\partial f_2}{\partial \theta} & \frac{\partial f_2}{\partial \varphi} \\ \frac{\partial f_3}{\partial \theta} & \frac{\partial f_3}{\partial \varphi} \end{pmatrix} = \begin{pmatrix} \frac{\partial f}{\partial \theta} & \frac{\partial f}{\partial \varphi} \end{pmatrix}$$

← 3 righe

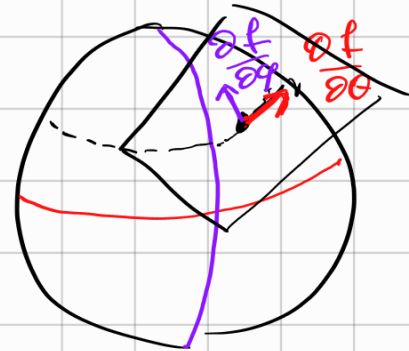
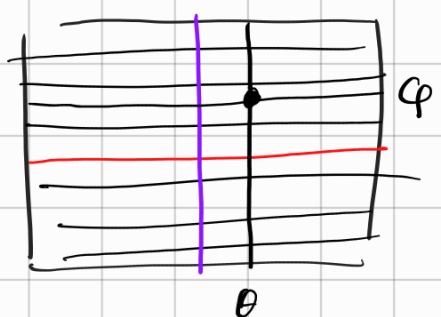
↑

2 colonne

nel nostro esempio =

$$\begin{pmatrix} -\cos \varphi \cdot \sin \theta & -\sin \varphi \cdot \cos \theta \\ \cos \varphi \cdot \cos \theta & -\sin \varphi \cdot \sin \theta \\ 0 & \cos \varphi \end{pmatrix}$$

↑ $\frac{\partial f}{\partial \theta}$ ↑ $\frac{\partial f}{\partial \varphi}$



Se $\gamma: \mathbb{R} \rightarrow \mathbb{R}^3$ $\gamma(t) = \gamma(t_0) + \gamma'(t_0) \cdot (t - t_0) + o(|t - t_0|)$

Casi particolari:

$\mu: x \rightarrow x_0$

prodotto tra numeri reali

$n=1, m=1$ $f(x) = f(x_0) + f'(x_0) \cdot (x - x_0) + o(|x - x_0|)$

↙ prodotto scalare tra vettori $x \in \mathbb{R}^2$

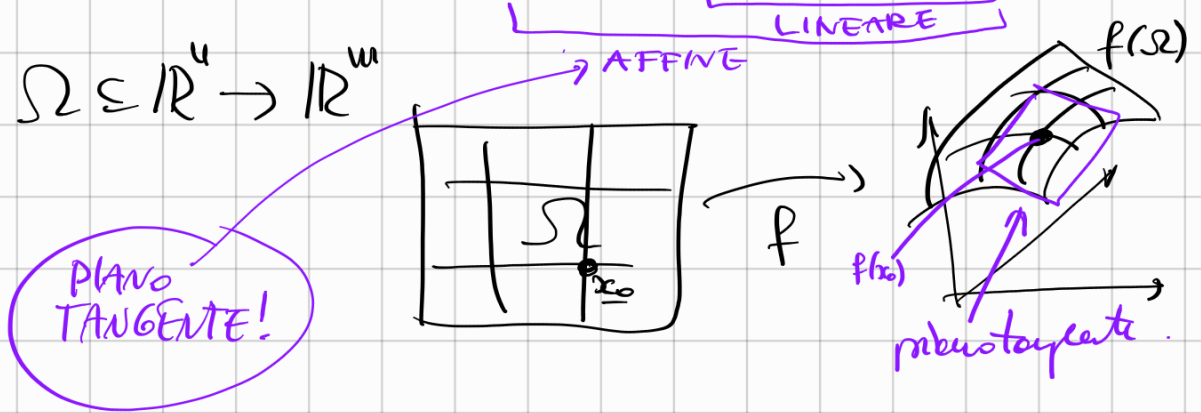
$n>1, m=1$ $f(\underline{x}) = f(\underline{x}_0) + \nabla f(\underline{x}_0) \cdot \begin{pmatrix} x - x_0 \\ \vdots \end{pmatrix} + o(|x - x_0|)$

$$m=1, m>1 \quad \underline{r}(t) = \underline{r}(t_0) + \underline{r}'(t_0) \cdot (t-t_0) + o(|t-t_0|)$$

← prodotto "per scalare"

$$m>1, m>1 \quad \text{caso generale} \quad \underline{f}(\underline{x}) = \underline{f}(\underline{x}_0) + \underline{Df}(\underline{x}_0) \cdot (\underline{x}-\underline{x}_0) + o(|\underline{x}-\underline{x}_0|)$$

$$\text{Se } f: \Omega \subseteq \mathbb{R}^n \rightarrow \mathbb{R}^m$$



Il piano tangente alla superficie $f(\Omega)$ nel punto $f(\underline{x}_0)$ è

$$\underline{f}(\underline{x}_0) + \text{Im } Df(\underline{x}_0)$$

spazio generato dalle colonne

$$\text{Im } Df(\underline{x}_0) = \left\langle \frac{\partial f}{\partial x_1}, \dots, \frac{\partial f}{\partial x_n} \right\rangle$$

$$\text{Se } f: \mathbb{R}^n \rightarrow \mathbb{R}$$

($m=1$)

Abbiamo una **forma di Taylor al II ordine**: $f \in C^2$.

$$f(\underline{x}) = f(\underline{x}_0) + \underbrace{\nabla f(\underline{x}_0)}_{\text{vettore } \mathbb{R}^n} \cdot \underbrace{(\underline{x}-\underline{x}_0)}_{\text{vettore } \mathbb{R}^n} + \frac{1}{2} \underbrace{(\underline{x}-\underline{x}_0)^T}_{1 \times n} \cdot \underbrace{D^2 f(\underline{x}_0)}_{n \times n} \cdot \underbrace{(\underline{x}-\underline{x}_0)}_{n \times 1} + o(|\underline{x}-\underline{x}_0|^2)$$

FORMA QUADRATICA

$$Hf(\underline{x}_0) = D^2 f(\underline{x}_0) = \begin{pmatrix} \frac{\partial^2 f}{\partial x_j \partial x_k} \end{pmatrix}_{n \times n}$$

↑ matrice Hessiana.

$$\frac{\partial}{\partial x_j} \frac{\partial f}{\partial x_k} = \frac{\partial^2 f}{\partial x_j \partial x_k}$$

Esempio $f(x, y, z) = x^2 + z - y^2$

$$\nabla f = \begin{pmatrix} \frac{\partial f}{\partial x} \\ \frac{\partial f}{\partial y} \\ \frac{\partial f}{\partial z} \end{pmatrix} = \begin{pmatrix} 2x \\ 2zy \\ y^2 \end{pmatrix}$$

$$D^2 f = \begin{pmatrix} \frac{\partial^2 f}{(\partial x)^2} & \frac{\partial^2 f}{\partial x \partial y} & \frac{\partial^2 f}{\partial x \partial z} \\ \frac{\partial^2 f}{\partial y \partial x} & \frac{\partial^2 f}{(\partial y)^2} & \frac{\partial^2 f}{\partial y \partial z} \\ \frac{\partial^2 f}{\partial z \partial x} & \frac{\partial^2 f}{\partial z \partial y} & \frac{\partial^2 f}{(\partial z)^2} \end{pmatrix} = \begin{pmatrix} 2 & 0 & 0 \\ 0 & 2z & 2y \\ 0 & 2y & 0 \end{pmatrix}$$

$$f = x^2 + zy^2 = f(0,0,0) + \nabla f(0,0,0) \cdot \begin{pmatrix} x \\ y \\ z \end{pmatrix} + \frac{1}{2} (x,y,z) D^2 f(0,0,0) \cdot \begin{pmatrix} x \\ y \\ z \end{pmatrix} + o(x^2+y^2+z^2)$$

$$\begin{pmatrix} x_0=0 \\ y_0=0 \\ z_0=0 \end{pmatrix}$$

$$= 0 + 0 + \frac{1}{2} (x,y,z) \begin{pmatrix} 2 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} + o(x^2+y^2+z^2)$$

$$= \frac{1}{2} (x,y,z) \cdot \begin{pmatrix} 2x \\ 0 \\ 0 \end{pmatrix} + o(x^2+y^2+z^2)$$

$$= \frac{1}{2} \cdot 2x^2 + o(x^2+y^2+z^2) = x^2 + o(x^2+y^2+z^2)$$

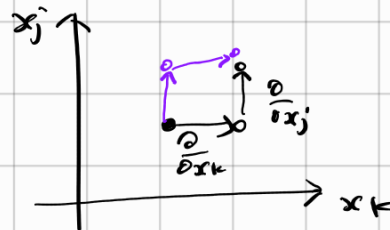
In effetti $zy^2 = o(x^2+y^2+z^2)$ infatti $\lim_{(x,y,z) \rightarrow (0,0,0)} \frac{zy^2}{x^2+y^2+z^2} = 0$

$$\begin{aligned} |z| = \sqrt{z^2} &\leq \sqrt{x^2+y^2+z^2} \\ |y| = \sqrt{y^2} &\leq \sqrt{x^2+y^2+z^2} \\ \left| \frac{zy^2}{x^2+y^2+z^2} \right| &\leq \left(\sqrt{x^2+y^2+z^2} \right)^{3-2} = \sqrt{x^2+y^2+z^2} \rightarrow 0 \end{aligned}$$

Teorema (Schwartz) Se $f \in C^2$ allora:

$$\frac{\partial}{\partial x_j} \left(\frac{\partial f}{\partial x_k} \right) = \frac{\partial}{\partial x_k} \left(\frac{\partial f}{\partial x_j} \right)$$

ovvero $Hf = D^2f$ è simmetrica.



Esempio $f(x,y) = x^2 \sin y$

$$\frac{\partial^2 f}{\partial y \partial x} \stackrel{?}{=} \frac{\partial^2 f}{\partial x \partial y} \quad \left\{ \begin{array}{l} \frac{\partial f}{\partial x} = 2x \cdot \sin y \\ \frac{\partial f}{\partial y} = x^2 \cdot \cos y \end{array} \right.$$

$$\frac{\partial^2 f}{\partial y \partial x} = \frac{\partial}{\partial y} \left(\frac{\partial f}{\partial x} \right) = \frac{\partial}{\partial y} (2x \sin y) = 2x \cdot \cos y$$

$$\frac{\partial^2 f}{\partial x \partial y} = \frac{\partial}{\partial x} \left(\frac{\partial f}{\partial y} \right) = \frac{\partial}{\partial x} (x^2 \cos y) = 2x \cdot \cos y$$

Esempio $f(x,y) = x^3 \cdot e^{xy} - y \cdot \sqrt{x}$

$$\left\{ \begin{array}{l} \frac{\partial f}{\partial x} = 3x^2 \cdot e^{xy} + x^3 \cdot e^{xy} - \frac{y^2}{2\sqrt{x}} = (3x^2 + x^3) e^{xy} - \frac{y^2}{2\sqrt{x}} \\ \frac{\partial f}{\partial y} = x^3 \cdot e^{xy} - 2y \cdot \sqrt{x} \end{array} \right.$$

$$\frac{\partial}{\partial y} \frac{\partial f}{\partial x} = (3x^2 + x^3) \cdot e^{xy} - \frac{y}{\sqrt{x}}$$

$$\frac{\partial}{\partial x} \frac{\partial f}{\partial y} = 3x^2 \cdot e^{xy} + x^3 \cdot e^{xy} - \frac{y}{\sqrt{x}} = (3x^2 + x^3) e^{xy} - \frac{y}{\sqrt{x}}$$



RICERCA DI MASSIMI E MINIMI (OTTIMIZZAZIONE)

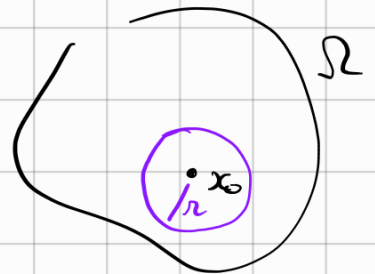
$$f: \Omega \subseteq \mathbb{R}^n \rightarrow \mathbb{R}$$

Un punto $x_0 \in \Omega$ si dice punto di massimo & (minimo)

$$f(x_0) \geq f(x) \quad \forall x \in \Omega$$

\Leftrightarrow x_0 si dice punto di massimo locale (o relativo) se esiste un $\varepsilon > 0$

$$\text{t.c. } f(x_0) \geq f(x) \quad \forall x \in \Omega: |x - x_0| < \varepsilon$$



Criteri per determinare tali punti.

Criterio al I ordine: Se $f \in C^1$ e se $x_0 \in \Omega$ è un punto INTERNO a Ω e se x_0 è un massimo o un minimo relativo allora:

$$\boxed{\nabla f(x_0) = \underline{0}} \quad \triangleleft \quad x_0 \text{ è un punto critico.}$$

dim Se ad esmpo x_0 è un punto di massimo:

$$\text{Eg. 2: } f(x) = f(x_0) + \nabla f(x_0) \cdot (x - x_0) + o(|x - x_0|)$$

$$f(x) \leq f(x_0) \quad \forall x \quad \text{t.c. } |x - x_0| < \varepsilon.$$

$$0 \geq f(x) - f(x_0) = \nabla f(x_0) \cdot (x - x_0) + o(|x - x_0|)$$

se presupp

$$x = x_0 + t \cdot \nabla f(x_0)$$

$$x - x_0 = t \cdot \nabla f(x_0)$$

$$t > 0$$

$$\begin{aligned}
 &= \nabla f(x_0) \cdot t \nabla f(x_0) + o\left(t \left| \nabla f(x_0) \right| \right) \\
 &= t \cdot \left| \nabla f(x_0) \right|^2 + o(t) \\
 &= t \left[\left| \nabla f(x_0) \right|^2 + o(1) \right] \quad t > 0
 \end{aligned}$$

se $\nabla f(x_0) \neq 0 \Rightarrow \left| \nabla f(x_0) \right| > 0$

per $t > 0$ abbastanza piccolo $\bar{e} \geq 0$.

Esempio Sia $f(x,y) = xy + x^2 + y^4$ $f: \mathbb{R}^2 \rightarrow \mathbb{R}$

Determinare, se esistono i punti di massimo e minimo di questa funzione.

se $x \rightarrow +\infty$

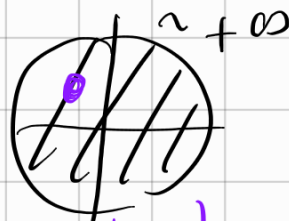
Si vede che non c'è un massimo assoluto: $f(x,y) = x^2 \rightarrow +\infty$

$$\sup f = +\infty$$

[in realtà $\lim_{\sqrt{x^2+y^2} \rightarrow \infty} f = +\infty$]

Ha minimo? (Intuitivamente sì, per Weierstrass)

Se (x_0, y_0) è punto di minimo



allora $\nabla f(x_0, y_0) = \underline{0}$ (è un punto critico)

$$f = xy + x^2 + y^4 \quad \nabla f = \begin{pmatrix} \frac{\partial f}{\partial x} \\ \frac{\partial f}{\partial y} \end{pmatrix} = \begin{pmatrix} y + 2x \\ x + 4y^3 \end{pmatrix}$$

$$\nabla f = \underline{0} \Leftrightarrow \begin{cases} y + 2x = 0 \\ x + 4y^3 = 0 \end{cases}$$

$$\begin{cases} y = -2x \\ x + 4(-2x)^3 = 0 \end{cases}$$

$$\begin{cases} y = -2x \\ x - 32x^3 = 0 \end{cases}$$

$$f = xy + x^2 + y^4$$

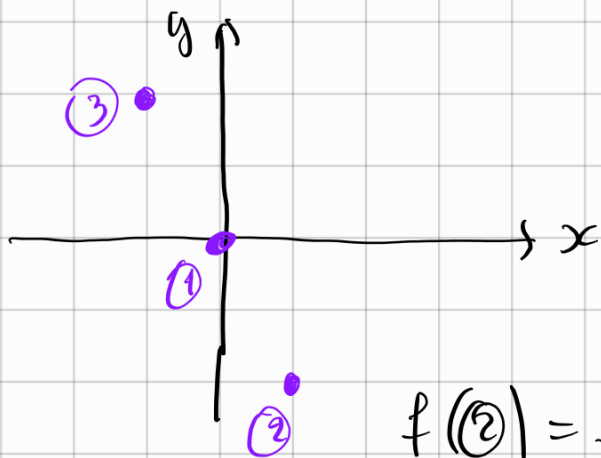
$$\begin{cases} y = -2x \\ x(1 - 32x^2) = 0 \end{cases}$$

$$\textcircled{1} \begin{cases} x = 0 \\ y = 0 \end{cases}$$

$$\textcircled{2} \begin{cases} x^2 = \frac{1}{32} \end{cases}$$

$$\textcircled{2} \begin{cases} x = \frac{1}{4\sqrt{2}} \\ y = -\frac{1}{2\sqrt{2}} \end{cases}$$

$$\textcircled{3} \begin{cases} x = -\frac{1}{4\sqrt{2}} \\ y = \frac{1}{2\sqrt{2}} \end{cases}$$



$$f(\textcircled{1}) = f(0,0) = 0$$

$$f(\textcircled{2}) = f\left(\frac{1}{4\sqrt{2}}, -\frac{1}{2\sqrt{2}}\right) = -\frac{1}{4\sqrt{2}} \frac{1}{2\sqrt{2}} + \frac{1}{32} + \frac{1}{64}$$

$$= -\frac{1}{16} + \frac{1}{32} + \frac{1}{64} = \frac{-4 + 2 + 1}{64} = -\frac{1}{64}$$

① non era minimo assoluto.

$$f(\textcircled{3}) = f\left(-\frac{1}{4\sqrt{2}}, \frac{1}{2\sqrt{2}}\right) = \dots = -\frac{1}{64}$$

Se c'è un minimo deve essere uno tra ② e ③ quindi entrambi sono minimi assoluti.

Condizione al II ordine $f \in C^2$

Se x_0 è un minimo ^(massimo) locale per f

allora la matrice $D^2f(x_0)$ ha tutti gli autovalori ≥ 0 .

$$\text{ES } f = xy + x^2 + y^4$$

$$Df = \begin{pmatrix} y + 2x \\ x + 4y^3 \end{pmatrix}$$

$$D^2 f = \begin{pmatrix} 2 & 1 \\ 1 & 12y^2 \end{pmatrix}$$

$$\det D^2 f = \lambda_1 - \lambda_2$$

$$t_2 D^2 f = \lambda_1 + \lambda_2$$

$$\det D^2 f = 24y^2 - 1$$

$$t_2 D^2 f = 2 + 12y^2$$

in (1) $x=0$
 $y=0$

$$\det = -1$$

$$\lambda_1 < 0$$

$$t_2 = 2$$

$$\lambda_2 > 0$$

in (2) e(3)

$$y^2 = \frac{1}{8}$$

$$D^2 f = \begin{pmatrix} 2 & 1 \\ 1 & \frac{3}{2} \end{pmatrix}$$

$$\left\{ \begin{array}{l} \det = 3 - 1 = 2 \\ t_2 = 2 + \frac{3}{2} = \frac{7}{2} \end{array} \right.$$

$$\lambda_1, \lambda_2 > 0$$

$$\lambda_1 + \lambda_2 > 0$$

$$\left\{ \begin{array}{l} \lambda_1 > 0 \\ \lambda_2 > 0 \end{array} \right. \Rightarrow \text{minimum locale.}$$