Bounded slope condition,

gradient estimate,

and up-to-the-boundary Lipschitz estimates for harmonic functions

BOUNDED SLOPE CONDITION

The bounded slope condition is a geometric condition on the graph of a function

$$g:\partial\Omega\to\mathbb{R}$$

Precisely, we have the following

Definizione 1 (Bounded slope condition). Let Ω be a bounded open set in \mathbb{R}^d and let $g : \partial \Omega \to \mathbb{R}$ be a continuous function. We say that g satisfies the bounded slope condition, if there is a constant S > 0 such that: for every $x_0 \in \partial \Omega$ there exist two vectors

$$\underline{\nu} \in B_1 \qquad e \qquad \overline{\nu} \in B_1,$$

such that

$$S \underline{\nu} \cdot (x - x_0) \le g(x) - g(x_0) \le S \overline{\nu} \cdot (x - x_0) \quad for \ all \quad x \in \partial\Omega.$$

Proposizione 2. A function $g: \partial \Omega \to \mathbb{R}$ that satisfies the bounded slope condition is Lipschitz continuous with Lipschitz constant S.

Dimostrazione. For every $x, y \in \partial \Omega$, we have

$$|S|\underline{\nu}||x-y| \le S \underline{\nu} \cdot (x-y) \le g(x) - g(y) \le s \overline{\nu} \cdot (x-y) \le S|\overline{\nu}||x-y|$$

Since $|\underline{\nu}| \leq 1$ and $|\overline{\nu}| \leq 1$ we have

$$-S|x-y| \le g(x) - g(y) \le S|x-y|$$

which concludes the proof.

Esercizio 3. Let Ω be an open set in \mathbb{R}^2 whose boundary $\partial\Omega$ contains the segment $\Gamma := (-1, 1) \times \{0\}$ (for instance, one such domain is the rectangle $(-1, 1) \times (0, 1)$).

• Prove that the function $g(x,y) = x^2$ does not satisfy the bounded slope condition on $\partial\Omega$.

• Prove that if $g: \partial \Omega \to \mathbb{R}$ satisfies the bounded slope condition, then $g: \Gamma \to \mathbb{R}$ is an affine function.

Proposizione 4. Let Ω be a convex bounded open set of class C^2 in \mathbb{R}^d . Moreover, suppose that there is a positive constant c > 0 such that at every boundary point $x_0 \in \partial \Omega$ the principle curvatures $\kappa_1(x_0), \ldots, \kappa_{d-1}(x_0)$ are bounded from below by c. Then, every function $g : \mathbb{R}^d \to \mathbb{R}$ of class C^2 satisfies the bounded slope condition on $\partial \Omega$.

Dimostrazione. Fix a point $X_0 \in \partial \Omega$ and consider the function

$$h(X) = g(X) - g(X_0) - (X - X_0) \cdot \nabla g(X_0).$$

Since Ω is a bounded C^2 domain, there is a radius R > 0 such that for every $X_0 \in \partial \Omega$ there is a function

$$\eta: B'_R \to (-R, R)$$

of class C^2 on the ball $B'_R \subset \mathbb{R}^{d-1}$ such that, up to a rotation and translation,

$$X_0 = 0, \quad \eta(0) = 0, \quad \nabla_{x'}\eta(0) = 0,$$

$$\Omega \cap \left(B'_R \times (-R, R)\right) = \left\{(x, y) \in B'_R \times (-R, R) : y > \eta(x)\right\},$$

$$\partial \Omega \cap \left(B'_R \times (-R, R)\right) = \left\{(x, \eta(x)) : x \in B'_R\right\}.$$

Assume for simplicity that d = 2. We proceed in several steps.

Step 1. Bounds on η' and η'' . We know that

$$\eta'' \ge 0 \quad \text{in} \quad (-R, R).$$

and that the curvature $\kappa : \partial \Omega \to \mathbb{R}$ of $\partial \Omega$ is given by

$$\kappa(x,\eta(x)) = \frac{\eta''(x)}{\left(1 + (\eta'(x))^2\right)^{3/2}}$$

By the lower bound on the curvature and the continuity of κ , there are constants c > 0 and C > 0 such that

$$0 < c \le \kappa \big(x, \eta(x) \big) \le C < +\infty$$

First we notice that

$$\eta'(0) = 0$$
 and $\eta' \ge 0$ on $(0, R)$

Moreover, if

$$\eta' \le \kappa \quad \text{on} \quad [0, L] \qquad \Rightarrow \qquad \eta''(x) \le (1 + \kappa^2)^{3/2} \frac{\eta''(x)}{\left(1 + (\eta'(x))^2\right)^{3/2}} \le C(1 + \kappa^2)^{3/2} \quad \text{on} \quad [0, L]$$
$$\Rightarrow \qquad \eta'(x) \le LC(1 + \kappa^2)^{3/2} \quad \text{on} \quad [0, L].$$

Thus, choosing

we get that

$$L := \min\left\{\frac{1}{8C}, R\right\},\,$$

 $\eta' \leq 1$ on [0, L].

By the same argument on [-L, 0], we get

 $|\eta'| \leq 1$ on [-L, L].

In particular, this implies the bounds

$$\frac{\eta''(x)}{\left(1+(\eta'(x))^2\right)^{3/2}} \le \eta''(x) \le 2^{3/2} \frac{\eta''(x)}{\left(1+(\eta'(x))^2\right)^{3/2}} \quad \text{for all} \quad x \in [-L, L],$$

so we get

$$c \le \eta''(x) \le 2^{3/2}C$$
 for all $x \in [-L, L]$

Step 2. An upper bound on $h(x, \eta(x))$ for $x \in [-L, L]$. We consider the function $v: [-L, L] \to \mathbb{R}$, $v(x) = h(x, \eta(x))$,

which is such that

$$v(0) = v'(0) = 0$$

$$v''(x) = h_{xx}(x,\eta(x)) + 2\eta'(x)h_{xy}(x,\eta(x)) + |\eta'(x)|^2 h_{yy}(x,\eta(x)) + \eta''(x)h_y(x,\eta(x))$$

= $g_{xx}(x,\eta(x)) + 2\eta'(x)g_{xy}(x,\eta(x)) + |\eta'(x)|^2 g_{yy}(x,\eta(x)) + \eta''(x)\Big(g_y(x,\eta(x)) - g_y(0,0)\Big)$

Since $g_{xx}, g_{xy}, g_{yy}, g_y$ are bounded functions, setting

$$\|\nabla^2 g\|_{L^{\infty}} = \sup \sqrt{g_{xx}^2 + 2g_{xy}^2 + g_{yy}^2}$$
 and $\|\nabla g\|_{L^{\infty}} = \sqrt{g_x^2 + g_y^2}$,

we get

and

$$|v''| \le 4 \|\nabla^2 g\|_{L^{\infty}} + 2C \|\nabla g\|_{L^{\infty}}$$

Thus, setting

$$A:=\frac{4\|\nabla^2 g\|_{L^\infty}+2C\|\nabla g\|_{L^\infty}}{c}$$

we get

$$|v''(x)| \le A\eta''(x)$$
 for all $x \in [-L, L]$.

This implies that

$$|h(x,\eta(x))| = |v(x)| \le A\eta(x) \quad \text{for all} \quad x \in [-L,L].$$

Step 3. An upper bound on $h : \partial \Omega \to \mathbb{R}$. By the lower bound

$$\eta''(x) \geq \frac{\eta''(x)}{\left(1 + (\eta'(x))^2\right)^{3/2}} \geq c,$$

we obtain that

Thus, setting

$$\eta(L) \ge \frac{c}{2}L^2 \quad \text{and} \quad \eta(-L) \ge \frac{c}{2}L^2$$
$$a := \inf\left\{L, \frac{c}{2}L^2\right\},$$

we get that there are points

$$\ell_{-} \in [-L, 0) \qquad \text{and} \qquad \ell_{+} \in (0, L]$$

such that

$$\eta(\ell_-) = \eta(\ell_+) = a.$$

Now, by the convexity of Ω we know that

$$\Omega \cap \left\{ (x,y) \in \mathbb{R}^2 : y \le a \right\} = \left\{ (x,y) \in \mathbb{R}^2 : \ell_- \le x \le \ell_+ , \eta(x) \le y \le a \right\}.$$

This implies the bound

$$|h(x,y)| \le Ay \quad \text{for all} \quad (x,y) \in \partial\Omega \cap \left\{ (x,y) \in \mathbb{R}^2 \ : \ y \le a \right\}$$

On the other hand, it is immediate to check that

$$|h(x,y)| \le \frac{\|g\|_{L^{\infty}(\partial\Omega)}}{a}y \quad \text{for all} \quad (x,y) \in \partial\Omega \cap \left\{(x,y) \in \mathbb{R}^2 : y \ge a\right\}.$$

Thus, there is a constant K, that depends on Ω and g, such that:

(1) $|h(x,y)| \le Ky \text{ for all } (x,y) \in \partial\Omega.$

Step 4. Conclusion. We recall that by the the definition of h, we get that

$$g(x,y) - g(0,0) = h(x,y) + (x,y) \cdot \nabla g(0,0).$$

Using the estimate (1), we get that

$$-Ky + (x, y) \cdot \nabla g(0, 0) \le g(x, y) - g(0, 0) \le Ky + (x, y) \cdot \nabla g(0, 0),$$

which can also be written as

$$(x,y) \cdot \Big(-Ke_2 + \nabla g(0,0) \Big) \le g(x,y) - g(0,0) \le (x,y) \cdot \Big(Ke_2 + \nabla g(0,0) \Big),$$

Finally, setting

$$S := K + \|\nabla g\|_{L^{\infty}(\partial\Omega)},$$

we get that g satisfies the bounded slope condition with slope S.

LIPSCHITZ REGULARITY UP TO THE BOUNDARY

Let Ω be a bounded open set in \mathbb{R}^d . Thanks to Proposition 2 we know that if $g : \partial\Omega \to \mathbb{R}$ is a function that satisfies the bounded slope condition on $\partial\Omega$, then it is Lipschitz continuous on $\partial\Omega$. Thus, it can be extended to a Lipschitz continuous function $\tilde{g} : \mathbb{R}^d \to \mathbb{R}$. As a consequence, there is a unique weak solution $h \in H^1(\Omega)$ of the problem

$$\Delta h = 0$$
 in Ω , $h = g$ on $\partial \Omega$,

in the sense that

$$h - \widetilde{g} \in H^1_0(\Omega)$$

and

$$\int_{\Omega} \nabla h \cdot \nabla \varphi \, dx = 0 \quad \text{for every} \quad \varphi \in C_c^{\infty}(\mathbb{R}^d).$$

We already know that h is C^{∞} in Ω and that

$$\Delta h(x) = 0$$
 for every $x \in \Omega$.

In this section we will prove that h is Lipschitz continuous on $\overline{\Omega}$ (with Lipschitz constant depending only on the slope of g and on the dimension of the space). We will only need that $g : \partial \Omega \to \mathbb{R}$ satisfies the bounded

slope condition as the proof does not require any further assumptions on the geometry or on the regularity of Ω . A key ingredient of the proof will be the following general result for harmonic functions.

Lemma 5 (Gradient estimate). Let $u \in C^{\infty}(B_R)$ be a harmonic function in a ball $B_R \subset \mathbb{R}^d$. Then

$$\|\nabla u\|_{L^{\infty}(B_{R/2})} \le \frac{2d}{R} \|u\|_{L^{\infty}(B_{R})}.$$

Dimostrazione. For every i = 1, ..., d, the partial derivative $\partial_i u : B_R \to \mathbb{R}$ is a harmonic function in B_R . In particular, for every constant unit vector $V = (v_1, ..., v_d) \in \mathbb{R}^d$, the function

$$V \cdot \nabla u : B_R \to \mathbb{R}$$
, $V \cdot \nabla u(x) = \sum_{j=1}^d v_j \partial_j u(x)$,

is harmonic in B_R and so it satisfies the mean value property

$$V \cdot \nabla u(x_0) = \int_{B_r(x_0)} V \cdot \nabla u(y) \, dy,$$

for every ball $B_r(x_0) \subset B_R$. Since we have the inclusion

$$B_{R/2}(x_0) \subset B_R$$
 for every $x_0 \in B_{R/2}$,

we get that

$$V \cdot \nabla u(x_0) = \int_{B_{R/2}(x_0)} V \cdot \nabla u(x) \, dx = \frac{2^d}{\omega_d R^d} \int_{B_{R/2}(x_0)} V \cdot \nabla u(x) \, dx \quad \text{for every} \quad x_0 \in B_{R/2}.$$

Now, by the divergence theorem

$$\int_{\Omega} \operatorname{div} X = \int_{\partial \Omega} X \cdot \nu$$

applied to the domain $\Omega := B_{R/2}(x_0)$ and to the vector field X(x) := u(x)V, we get

$$\int_{B_{R/2}(x_0)} V \cdot \nabla u(x) \, dx = \int_{\partial B_{R/2}(x_0)} u(x) V \cdot \nu(x) \, d\mathcal{H}^{d-1}(x)$$

where $\nu(x) := x/R$ is the exterior normal to $\partial B_{R/2}(x_0)$. Finally, using that

$$|u(x)V \cdot \nu(x)| \le |u(x)|$$
 on $\partial B_{R/2}(x_0)$,

and putting the above estimates together, we get

$$\begin{aligned} |V \cdot \nabla u(x_0)| &= \frac{2^d}{\omega_d R^d} \left| \int_{B_{R/2}(x_0)} V \cdot \nabla u(y) \, dy \right| \\ &= \frac{2^d}{\omega_d R^d} \left| \int_{\partial B_{R/2}(x_0)} u \, V \cdot \nu \, d\mathcal{H}^{d-1} \right| \\ &\leq \frac{2d}{R} \|u\|_{L^{\infty}(\partial B_{R/2}(x_0))} \\ &\leq \frac{2d}{R} \|u\|_{L^{\infty}(B_R)} \, . \end{aligned}$$

Since $x_0 \in B_{R/2}$ and $V \in \partial B_1$ is arbitrary, this concludes the proof.

Teorema 6 (Bounded slope condition and Lipschitz regularity up to the boundary). Let Ω be a bounded open set in \mathbb{R}^d and let $g: \partial \Omega \to \mathbb{R}$ be a function that satisfies the bounded slope condition with slope S > 0 on $\partial \Omega$. Let $h \in H^1(\Omega)$ be the weak solution to the problem

$$\Delta h = 0 \quad in \quad \Omega \ , \qquad h = g \quad su \quad \partial \Omega$$

Then, there is a dimensional constant C_d such that

$$|\nabla h| \le C_d S \qquad on \qquad \Omega,$$

and such that the function

$$\widetilde{h}:\overline{\Omega}\to\mathbb{R}\;,\qquad \widetilde{h}(x):=\begin{cases} h(x) & \text{if} \quad x\in\Omega,\\ g(x) & \text{if} \quad x\in\partial\Omega, \end{cases}$$

is Lipschitz continuous on $\overline{\Omega}$ with Lipschitz constant C_dS .

Dimostrazione. We know that h is C^{∞} in Ω . We will first prove that $|\nabla h|$ is bounded in Ω . Consider a point $x_0 \in \Omega$ and let y_0 be a projection of x_0 on $\partial \Omega$. Setting

$$R_0 := |x_0 - y_0|$$

we get that $B_{R_0}(x_0) \subset \Omega$. Then, by the gradient estimate in $B_{R_0}(x_0)$ applied to the harmonic function

$$x \mapsto h(x) - g(y_0)$$

we get that

$$|\nabla h(x_0)| \le \frac{2d}{R_0} ||h - g(y_0)||_{L^{\infty}(B_{R_0}(x_0))}.$$

Now, since g satisfied the bounded slope condition on $\partial \Omega$ we have that

$$S \underline{\nu} \cdot (y - y_0) \le g(y) - g(y_0) \le S \overline{\nu} \cdot (y - y_0)$$
 for all $y \in \partial \Omega$

for some vectors $|\underline{\nu}| \leq 1$ and $|\overline{\nu}| \leq 1$. Since the functions

$$x \mapsto S \, \underline{\nu} \cdot (x - y_0)$$
 and $x \mapsto S \, \overline{\nu} \cdot (x - y_0)$

are harmonic on Ω , the (weak) maximum principle gives

$$S \underline{\nu} \cdot (x - y_0) \le h(x) - g(y_0) \le S \overline{\nu} \cdot (x - y_0)$$
 for all $y \in \partial \Omega$,

so that

 $|h(x) - g(y_0)| \le S |x - y_0|$ for all $x \in \Omega$.

In particular, for every $x \in B_{R_0}(x_0)$ we have

$$|h(x) - g(y_0)| \le S |x - y_0| \le S 2R_0$$

which combined with the gradient estimate provides

$$|\nabla h(x_0)| \le \frac{2d}{R_0} ||h - g(y_0)||_{L^{\infty}(B_{R_0}(x_0))} \le \frac{2d}{R_0} 2SR_0 = 4dS.$$

Since $x_0 \in \Omega$ was arbitrary, we get

(2)
$$|\nabla h| \le 2dS$$
 in Ω .

We next prove that h is Lipschitz continuous up to the boundary. Let x_1 and x_2 be two points in $\overline{\Omega}$, let

$$\delta_1 := \operatorname{dist}(x_1, \partial \Omega) , \quad \delta_2 := \operatorname{dist}(x_2, \partial \Omega)$$

and let y_1 and y_2 be two points on $\partial\Omega$ that realize the distances δ_1 and δ_2 respectively. Without loss of generality we can suppose that $|x_1 - y_1| = \delta_1 < \delta_2 = |x_2 - y_2|.$

$$\delta_2 \le |x_2 - y_1| \le |x_1 - x_2| + \delta_1$$

We consider two cases.

Case 1. $|x_1 - x_2| \leq 10\delta_1$. Then, the ball of center x_1 and radius $r = 2|x_1 - x_2|$ is contained in Ω . Applying the estimate (2) in $B_r(x_1)$ we get that

$$|h(x_1) - h(x_2)| \le \|\nabla h\|_{L^{\infty}(B_r)} |x_1 - x_2| \le 4dS |x_1 - x_2|.$$

Case 2. $|x_1 - x_2| \ge 10\delta_1$. Then, the ball with center y_1 and radius $R = 2|x_1 - x_2|$ contains both x_1 and x_2 . Indeed,

$$|x_1 - y_1| = \delta_1 \le |x_1 - x_2|$$

and

$$|x_2 - y_1| \le |x_1 - x_2| + |x_1 - y_1| \le |x_1 - x_2| + \delta_1 \le 2|x_1 - x_2|.$$

Now, we use again the bounded slope condition on g and the maximum principle. By the bounded slope condition, there are vectors $\underline{\nu}$ and $\overline{\nu}$ such that

$$S \underline{\nu} \cdot (y - y_1) \le g(y) - g(y_1) \le S \overline{\nu} \cdot (y - y_1)$$
 for all $y \in \partial \Omega$.

Since the functions

$$x \mapsto S \underline{\nu} \cdot (x - y_1)$$
 and $x \mapsto S \overline{\nu} \cdot (x - y_1)$

are harmonic on Ω , the (weak) maximum principle gives

$$S \,\underline{\nu} \cdot (x - y_1) \leq h(x) - g(y_1) \leq S \,\overline{\nu} \cdot (x - y_1) \quad \text{for all} \quad y \in \partial\Omega.$$

Combining the estimates for $g - g(y_1)$ on the boundary and $h - g(y_1)$ in Ω , we get
$$|\tilde{h}(x) - g(y_1)| \leq S |x - y_1| \quad \text{for all} \quad x \in \overline{\Omega}.$$

Thus,

$$\begin{split} |\widetilde{h}(x_2) - \widetilde{h}(x_1)| &\leq |\widetilde{h}(x_1) - g(y_1)| + |\widetilde{h}(x_2) - g(y_1)| \\ &\leq S |x_1 - y_1| + S |x_2 - y_1| \\ &\leq 3S |x_1 - x_2|. \end{split}$$

In conclusion, since $4d\geq 3,$ combining the two cases above, we get that

$$|\widetilde{h}(x_2) - \widetilde{h}(x_1)| \le 4dS|x_1 - x_2|,$$

which concludes the proof.