# SYMMETRY RESULTS FOR NONLINEAR ELLIPTIC OPERATORS WITH UNBOUNDED DRIFT 

ALBERTO FARINA, MATTEO NOVAGA, ANDREA PINAMONTI


#### Abstract

We prove the one-dimensional symmetry of solutions to elliptic equations of the form $-\operatorname{div}\left(e^{G(x)} a(|\nabla u|) \nabla u\right)=f(u) e^{G(x)}$, under suitable energy conditions. Our results holds without any restriction on the dimension of the ambient space.


## Contents

1. Introduction ..... 1
2. A geometric Poincaré inequality ..... 4
3. One-dimensional symmetry of solutions ..... 8
4. Solutions with Morse index bounded by the euclidean dimension ..... 11
References ..... 13

## 1. Introduction

In this paper we study the one-dimensional symmetry of solutions to nonlinear equations of the following type:

$$
\begin{equation*}
\operatorname{div}(a(|\nabla u|) \nabla u)+a(|\nabla u|)\langle\nabla G(x), \nabla u\rangle+f(u)=0 \tag{1}
\end{equation*}
$$

or in a more compact form

$$
\begin{equation*}
-\operatorname{div}\left(e^{G(x)} a(|\nabla u|) \nabla u\right)=f(u) e^{G(x)}, \tag{2}
\end{equation*}
$$

where $f \in C^{1}(\mathbb{R})^{1}, G \in C^{2}\left(\mathbb{R}^{n}\right)$ and $a \in C_{l o c}^{1,1}((0,+\infty))$. We also require that the function $a$ satisfies the following structural conditions:

$$
\begin{align*}
& a(t)>0 \quad \text { for any } t \in(0,+\infty)  \tag{3}\\
& a(t)+a^{\prime}(t) t>0 \quad \text { for any } t \in(0,+\infty) \tag{4}
\end{align*}
$$

[^0]Observe that the general form of (2) encompasses, as very special cases, many elliptic singular and degenerate equations. Indeed, if $G \equiv 0$ and $a(t)=t^{p-2}, 1<p<+\infty$, or $a(t)=1 / \sqrt{1+t^{2}}$ then we obtain the $p$-Laplacian and the mean curvature equations respectively. Moreover, if $a(t) \equiv 1$ and $G(x)=-|x|^{2} / 2$ equation (1) boils down to the classical Ornstein-Uhlenbeck operator for which we refer to [1] and the references therein.

To prove the one-dimensional symmetry of solutions we follow the approach introduced in [5] and further developed in [9].

Following [5, 9, 3], we define $A: \mathbb{R}^{n} \rightarrow \operatorname{Mat}(n \times n), \lambda_{1} \in C^{0}((0,+\infty)), \lambda_{G} \in C^{0}\left(\mathbb{R}^{2 n}\right)$ as follow

$$
\begin{gather*}
A_{h k}(\xi):=\frac{a^{\prime}(|\xi|)}{|\xi|} \xi_{h} \xi_{k}+a(|\xi|) \delta_{h k} \quad \text { for any } 1 \leq h, k \leq n  \tag{5}\\
\lambda_{1}(t):=a(t)+a^{\prime}(t) t \quad \text { for any } t>0
\end{gather*}
$$

and

$$
\begin{equation*}
\lambda_{G}(x):=\text { maximal eigenvalue of } \nabla^{2} G(x) \tag{7}
\end{equation*}
$$

Definition 1.1. We say that $u$ is a weak solution to (1) if $u \in C^{1}\left(\mathbb{R}^{n}\right)$ and denoted by $\mathrm{d} \mu=e^{G(x)} \mathrm{d} x$

$$
\begin{equation*}
\int_{\mathbb{R}^{n}}\langle a(|\nabla u|) \nabla u, \nabla \varphi\rangle-f(u) \varphi \mathrm{d} \mu=0 \quad \forall \varphi \in C_{c}^{1}\left(\mathbb{R}^{n}\right) \tag{8}
\end{equation*}
$$

and either (A1) or (A2) is satisfied, where :
(A1) $\{\nabla u=0\}=\emptyset$.
(A2) $a \in C^{0}([0,+\infty))$ and

$$
\text { the map } \quad t \rightarrow t a(t) \quad \text { belongs to } \quad C^{1}([0,+\infty)) .
$$

Notice that (8) is well-defined, thanks to (A1) or (A2).
Notice also that weak solutions to (1) are critical points of the functional

$$
\begin{equation*}
I(u):=\int_{\mathbb{R}^{n}}(\Lambda(|\nabla u|)+F(u)) \mathrm{d} \mu \tag{9}
\end{equation*}
$$

where $F^{\prime}(t)=-f(t), \mathrm{d} \mu=e^{G(x)} \mathrm{d} x$ and

$$
\Lambda(t):=\int_{0}^{t} a(|\tau|) \tau \mathrm{d} \tau
$$

The regularity assumption $u \in C^{1}\left(\mathbb{R}^{n}\right)$ is always fulfilled in many important cases, like those involving the $p$-Laplacian operator or the mean curvature operator. For instance, when $a(t)=t^{p-2}, 1<p<+\infty$, any distribution solution $u \in W_{l o c}^{1, p}\left(\mathbb{R}^{n}\right) \cap L_{l o c}^{\infty}\left(\mathbb{R}^{n}\right)$ is of class $C^{1}$, by the well-known results in $[16,22]$ ). In light of this, and in view of the great generality of the function $a$, it is natural to work in the above setting.

Definition 1.2. Let $h \in L_{l o c}^{1}\left(\mathbb{R}^{n}\right)$ and let $u$ be a weak solution to (1). We say that $u$ is $h$-stable if

$$
\begin{equation*}
\int_{\mathbb{R}^{n}}\langle A(\nabla u) \nabla \varphi, \nabla \varphi\rangle-f^{\prime}(u) \varphi^{2} \mathrm{~d} \mu \geq \int_{\mathbb{R}^{n}} a(|\nabla u|) h \varphi^{2} \mathrm{~d} \mu \quad \forall \varphi \in C_{c}^{1}\left(\mathbb{R}^{n}\right) \tag{10}
\end{equation*}
$$

Remark 1.3. When $a(t) \equiv 1$, Definition 1.2 boils down to the $h$-stability condition introduced in $[2,3]$.

When $h \equiv 0$, then $u$ satisfies the classical stability condition $[5,9,11,10]$, and
we simply say that $u$ is stable. In particular,
every minimum point of the functional (9) is a stable solution to (1).
Let us also point out that, in view of (A1) or (A2), the integral

$$
\begin{equation*}
\int_{\mathbb{R}^{n}}\langle A(\nabla u) \nabla \varphi, \nabla \varphi\rangle-f^{\prime}(u) \varphi^{2}-a(|\nabla u|) h \varphi^{2} \mathrm{~d} \mu \tag{11}
\end{equation*}
$$

is well defined. ${ }^{2}$ In particular, under the condition (A2) the function $A$ can be extended by continuity at the origin, by setting $A_{h k}(0):=a(0) \delta_{h k}$.

We can now state our main symmetry results:
Theorem 1. Assume $G \in C^{2}\left(\mathbb{R}^{n}\right)$ and $h \in L_{\text {loc }}^{1}\left(\mathbb{R}^{n}\right)$ with $h \geq \lambda_{G}$. Let $u \in C^{1}\left(\mathbb{R}^{n}\right) \cap$ $C^{2}(\{\nabla u \neq 0\})$ with $\nabla u \in H_{l o c}^{1}\left(\mathbb{R}^{n}\right)$ be a $h$-stable weak solution to (1).

Assume that there exists $C>0$ such that

$$
\begin{equation*}
\lambda_{1}(t) \leq C a(t) \quad \forall t>0 \tag{12}
\end{equation*}
$$

and one of the following conditions holds
(a) there exists $C_{0} \geq 1$ such that $\int_{B_{R}} a(|\nabla u|)|\nabla u|^{2} \mathrm{~d} \mu \leq C_{0} R^{2}$ for any $R \geq C_{0}$,
(b) $n=2$ and $u$ satisfies $a(|\nabla u|)|\nabla u|^{2} e^{G} \in L^{\infty}\left(\mathbb{R}^{2}\right)$.

Then $u$ is one-dimensional, i.e. there exists $\omega \in \mathbb{S}^{n-1}$ and $u_{0}: \mathbb{R} \rightarrow \mathbb{R}$ such that

$$
\begin{equation*}
u(x)=u_{0}(\langle\omega, x\rangle) \quad \forall x \in \mathbb{R}^{n} \tag{13}
\end{equation*}
$$

Moreover,

$$
\begin{equation*}
\left\langle\left(h(x) \mathrm{I}_{n}-\nabla^{2} G(x)\right) \nabla u, \nabla u\right\rangle=0 \quad \forall x \in \mathbb{R}^{n} \tag{14}
\end{equation*}
$$

In particular, if $u_{0}$ is not constant, there are $C$ and $g$ of class $C^{2}$ such that

$$
\begin{equation*}
G(x)=C(\langle\omega, x\rangle)+g\left(x^{\prime}\right) \tag{15}
\end{equation*}
$$

where $x^{\prime}:=x-\langle\omega, x\rangle \omega$ and $\lambda_{G}(x)=h(x)=C^{\prime \prime}(\langle\omega, x\rangle)$ for all $x \in \mathbb{R}^{n}$.

[^1]Remark 1.4. Paradigmatic examples satisfying the assumption (12) are the $p$-Laplacian operator, for any $p \in(1,+\infty)$, and the generalized mean curvature operator obtained by setting $a(t):=\left(1+t^{q}\right)^{-\frac{1}{q}}$, with $q>1$.

Theorem 2. Let $G(x):=-|x|^{2} / 2, a(t):=t^{p-2}$ with $p>1$ and let $u \in C^{1}\left(\mathbb{R}^{n}\right) \cap W^{1, \infty}\left(\mathbb{R}^{n}\right)$ be a monotone weak solution to (1), i.e., such that

$$
\begin{equation*}
\partial_{i} u(x)>0 \quad \forall x \in \mathbb{R}^{n}, \tag{16}
\end{equation*}
$$

for some $i \in\{1, \ldots, n\}$. Suppose that $u$ satisfies either (a) or (b) in Theorem 1. Then $u$ is one-dimensional. Moreover, if either $p=2$ or $a(t):=\left(1+t^{q}\right)^{-\frac{1}{q}}$ with $q>1$, then the same conclusion holds for every monotone weak solution $u \in C^{1}\left(\mathbb{R}^{n}\right) \cap L^{\infty}\left(\mathbb{R}^{n}\right)$.

Theorem 3. Let $u$ be a bounded weak solution to

$$
\begin{equation*}
\Delta u-\langle x, \nabla u\rangle+f(u)=0 \tag{17}
\end{equation*}
$$

with Morse index $k$. Then,
(i) if $k \leq 2$ then $u$ is one-dimensional;
(ii) if $3 \leq k \leq n$ then $u$ is a function of at most $k-1$ variables, i.e. there exists $C \in \operatorname{Mat}((k-1) \times n)$ and $u_{0}: \mathbb{R}^{k-1} \rightarrow \mathbb{R}$ such that

$$
\begin{equation*}
u(x)=u_{0}(C x) \quad \forall x \in \mathbb{R}^{n} \tag{18}
\end{equation*}
$$

The result in Theorem 3 should be compared with the analysis in [14], where the author shows that a minimal surface in the Gauss space, with Morse index less than or equal to $n$, is necessarily a hyperplane through the origin. These minimal surfaces are important geometric objects as they correspond to self-shrinkers for the mean curvature flow, which are the model of generic singularities. Since the minimal surface equation in the Gauss space arises as singular limit, as $\epsilon \rightarrow 0$, of the equations

$$
\Delta u-\langle x, \nabla u\rangle-\frac{W^{\prime}(u)}{\epsilon}=0
$$

where $W$ is a double-well potential (see for instance [23]), it is natural to ask if there exist bounded solutions to (17), with Morse index less than or equal to $n$, which are not one-dimensional.

## 2. A geometric Poincaré inequality

We recall the following result which has been proved in [9].
Lemma 2.1. For any $\xi \in \mathbb{R}^{n} \backslash\{0\}$, the matrix $A(\xi)$ is symmetric and positive definite and its eigenvalues are $\lambda_{1}(|\xi|), \cdots, \lambda_{n}(|\xi|)$, where $\lambda_{1}$ is as in (6) and $\lambda_{i}(t)=a(t)$ for every $i=2, \ldots, n$. Moreover,

$$
\begin{equation*}
\langle A(\xi) \xi, \xi\rangle=|\xi|^{2} \lambda_{1}(|\xi|) \tag{19}
\end{equation*}
$$

and

$$
\begin{equation*}
0 \leq\langle A(\xi)(V-W),(V-W)\rangle=\langle A(\xi) V, V\rangle+\langle A(\xi) W, W\rangle-2\langle A(\xi) V, W\rangle \tag{20}
\end{equation*}
$$

for any $V, W \in \mathbb{R}^{n}$ and any $\xi \in \mathbb{R}^{n} \backslash\{0\}$.

Lemma 2.2. Let $u \in C^{1}\left(\mathbb{R}^{n}\right) \cap C^{2}(\{\nabla u \neq 0\})$ with $\nabla u \in H_{l o c}^{1}\left(\mathbb{R}^{n}\right)$ be a weak solution to (1). Then for any $i=1, \ldots, n$, and any $\varphi \in C_{c}^{1}\left(\mathbb{R}^{n}\right)$ we have

$$
\begin{equation*}
\int_{\mathbb{R}^{n}}\left\langle A(\nabla u) \nabla u_{i}, \nabla \varphi\right\rangle-a(|\nabla u|)\left\langle\nabla u, \nabla\left(G_{i}\right)\right\rangle \varphi-f^{\prime}(u) u_{i} \varphi \mathrm{~d} \mu=0 \tag{21}
\end{equation*}
$$

Proof. By Lemma 2.2 in [9] we have

$$
\begin{equation*}
\text { the map } \quad x \rightarrow W(x):=a(|\nabla u(x)|) \nabla u(x) \quad \text { belongs to } W_{l o c}^{1,1}\left(\mathbb{R}^{n}, \mathbb{R}^{n}\right) \tag{22}
\end{equation*}
$$

therefore, since $e^{G(x)} \in C^{2}\left(\mathbb{R}^{n}\right)$ we get

$$
\begin{equation*}
W e^{G} \in W_{l o c}^{1,1}\left(\mathbb{R}^{n}, \mathbb{R}^{n}\right) \tag{23}
\end{equation*}
$$

By Stampacchia's Theorem (see, e.g. [18, Theorem 6:19]), we get $\partial_{i}\left(W e^{G}\right)=0$ for almost any $x \in\left\{W e^{G}=0\right\}=\{W=0\}$, that is

$$
\partial_{i}\left(W e^{G}\right)=0
$$

for almost any $x \in\{\nabla u=0\}$. In the same way, by Stampacchia's Theorem and (A2), it can be proven that $\nabla u_{i}(x)=0$, and hence $A(\nabla u(x)) \nabla u_{i}(x)=0$, for almost any $x \in\{\nabla u=0\}$. Moreover, the following relation holds (see [9] for the proof)

$$
\begin{equation*}
\partial_{i}\left(W e^{G}\right)=\left(A(\nabla u) \nabla u_{i}+a(|\nabla u|) \nabla u G_{i}\right) e^{G} \quad \text { on }\{\nabla u \neq 0\} \tag{24}
\end{equation*}
$$

and thanks to the previous observations

$$
\begin{equation*}
\partial_{i}\left(W e^{G}\right)=\left(A(\nabla u) \nabla u_{i}+a(|\nabla u|) \nabla u G_{i}\right) e^{G} \quad \text { a.e. in } \mathbb{R}^{n} . \tag{25}
\end{equation*}
$$

Applying (8) with $\varphi$ replaced by $\varphi_{i}$ and making use of (23) and (25), we obtain

$$
\begin{aligned}
0 & =\int_{\mathbb{R}^{n}} a(|\nabla u|)\left\langle\nabla u, \nabla \varphi_{i}\right\rangle-f(u) \varphi_{i} \mathrm{~d} \mu \\
& =\int_{\mathbb{R}^{n}}-\left\langle A(\nabla u) \nabla u_{i}, \nabla \varphi\right\rangle-a(|\nabla u|)\langle\nabla u, \nabla \varphi\rangle G_{i} \mathrm{~d} \mu \\
& +\int_{\mathbb{R}^{n}} f^{\prime}(u) u_{i} \varphi+f(u) \varphi G_{i} \mathrm{~d} \mu \\
& =\int_{\mathbb{R}^{n}}-\left\langle A(\nabla u) \nabla u_{i}, \nabla \varphi\right\rangle-a(|\nabla u|)\left\langle\nabla u, \nabla\left(\varphi G_{i}\right)\right\rangle \mathrm{d} \mu \\
& +\int_{\mathbb{R}^{n}} a(|\nabla u|)\left\langle\nabla u, \nabla G_{i}\right\rangle \varphi+f^{\prime}(u) u_{i} \varphi+f(u) \varphi G_{i} \mathrm{~d} \mu
\end{aligned}
$$

Recalling (8), applied with $\varphi$ replaced by $\varphi G_{i}$, we obtain the thesis.
From now on, we use $A$ and $a$, as a short-hand notation for $A(\nabla u)$ and $a:=a(|\nabla u|)$ respectively. In the following result we prove that every monotone solution to (1) is indeed $h$-stable.

Lemma 2.3. Assume that $u$ is a weak solution to (1) and that there exists $i \in\{1, \ldots, n\}$ such that

$$
\begin{equation*}
u_{i}:=\partial_{i} u(x)>0 \quad \forall x \in \mathbb{R}^{n} \tag{26}
\end{equation*}
$$

then $u$ is $h$-stable, with

$$
h(x):=\frac{\left\langle\nabla u(x), \nabla G_{i}(x)\right\rangle}{u_{i}(x)}
$$

Proof. Let $\varphi \in C_{c}^{\infty}\left(\mathbb{R}^{n}\right)$ and $\psi:=\varphi^{2} / u_{i}$. We use (20) with $V:=\varphi \nabla u_{i} / u_{i}$ and $W:=\nabla \varphi$ to obtain that

$$
\frac{2 \varphi}{u_{i}}\left\langle A \nabla u_{i}, \nabla \varphi\right\rangle-\frac{\varphi^{2}}{u_{i}^{2}}\left\langle A \nabla u_{i}, \nabla u_{i}\right\rangle \leq\langle A \nabla \varphi, \nabla \varphi\rangle .
$$

From this and Lemma 2.2 we get

$$
\begin{align*}
0 & =\int\left\langle A \nabla u_{i}, \nabla \psi\right\rangle-a\left\langle\nabla u, \nabla G_{i}\right\rangle \psi-f^{\prime}(u) u_{i} \psi \mathrm{~d} \mu  \tag{27}\\
& =\int 2 \frac{\varphi}{u_{i}}\left\langle A \nabla u_{i}, \nabla \varphi\right\rangle-\frac{\varphi^{2}}{u_{i}^{2}}\left\langle A \nabla u_{i}, \nabla u_{i}\right\rangle-a \frac{\varphi^{2}}{u_{i}}\left\langle\nabla u, \nabla G_{i}\right\rangle-f^{\prime}(u) \varphi^{2} \mathrm{~d} \mu \\
& \leq \int\langle A \nabla \varphi, \nabla \varphi\rangle-a \frac{\varphi^{2}}{u_{i}}\left\langle\nabla u, \nabla G_{i}\right\rangle-f^{\prime}(u) \varphi^{2} \mathrm{~d} \mu
\end{align*}
$$

Notice that we can apply Lemma 2.2 since, in view of (26), $u$ has no critical points and thus it is of class $C^{2}$, by the classical regularity results.

The following Lemma can be proved using the same tecniques implemented in [9, Lemma 2.4],

Lemma 2.4. Let $h \in L_{l o c}^{1}\left(\mathbb{R}^{n}\right)$. Let $u \in C^{1}\left(\mathbb{R}^{n}\right) \cap C^{2}(\{\nabla u \neq 0\})$ with $\nabla u \in H_{l o c}^{1}\left(\mathbb{R}^{n}\right)$ be a $h$-stable weak solution to (1). Then, (10) holds for any $\varphi \in H_{0}^{1}(B)$ and for any ball $B \subset \mathbb{R}^{n}$. Moreover, under the assumptions of Lemma 2.2,

$$
\begin{equation*}
\int_{\mathbb{R}^{n}}\left\langle A(\nabla u) \nabla u_{i}, \nabla \varphi\right\rangle-a(|\nabla u|)\left\langle\nabla u, \nabla\left(G_{i}\right)\right\rangle \varphi-f^{\prime}(u) u_{i} \varphi \mathrm{~d} \mu=0 \tag{28}
\end{equation*}
$$

for any $i=1, \ldots, n$, any $\varphi \in H_{0}^{1}(B)$ and any ball $B \subset \mathbb{R}^{n}$.
Proposition 2.5. Let $h \in L_{l o c}^{1}\left(\mathbb{R}^{n}\right)$ and $u \in C^{1}\left(\mathbb{R}^{n}\right) \cap C^{2}(\{\nabla u \neq 0\})$ with $\nabla u \in H_{l o c}^{1}\left(\mathbb{R}^{n}\right)$ be a $h$-stable weak solution to (1). Then, for every $\varphi \in C_{c}^{1}\left(\mathbb{R}^{n}\right)$ it holds

$$
\begin{align*}
\int_{\mathbb{R}^{n}} a(|\nabla u|) h(x)|\nabla u|^{2} \varphi^{2} \mathrm{~d} \mu & \leq \int_{\mathbb{R}^{n}}|\nabla u|^{2}\langle A \nabla \varphi, \nabla \varphi\rangle+a(|\nabla u|)\left\langle\nabla^{2} G \nabla u, \nabla u\right\rangle \varphi^{2}  \tag{29}\\
& +\varphi^{2}\left[\langle A \nabla| \nabla u|, \nabla| \nabla u| \rangle-\sum_{i=1}^{n}\left\langle A(\nabla u) \nabla u_{i}, \nabla u_{i}\right\rangle\right] \mathrm{d} \mu
\end{align*}
$$

Proof. We start observing that by Stampacchia's Theorem, since $\mu \ll \mathcal{L}^{n}$, we get

$$
\begin{align*}
& \nabla|\nabla u|(x)=0 \quad \mu \text { - a.e. } x \in\{|\nabla u|=0\}  \tag{30}\\
& \nabla u_{j}(x)=0 \quad \mu \text { - a.e. } x \in\{|\nabla u|=0\} \subseteq\left\{u_{j}=0\right\} \tag{31}
\end{align*}
$$

for any $j=1, \ldots, n$. Let $\varphi \in C_{c}^{1}\left(\mathbb{R}^{n}\right)$ and $i=1, \ldots, n$. Using (21) with test function $u_{i} \varphi^{2}$ and summing over $i=1, \ldots, n$ we get

$$
\begin{equation*}
\int_{\mathbb{R}^{n}} \sum_{i=1}^{n}\left\langle A(\nabla u) \nabla u_{i}, \nabla\left(u_{i} \varphi^{2}\right)\right\rangle-f^{\prime}(u)|\nabla u|^{2} \varphi^{2} \mathrm{~d} \mu=\int_{\mathbb{R}^{n}} a(|\nabla u|)\left\langle\nabla^{2} G \nabla u, \nabla u\right\rangle \varphi^{2} \mathrm{~d} \mu \tag{32}
\end{equation*}
$$

Using (10) with test function $|\nabla u| \varphi$ (note that this choice is possible thanks to Lemma 2.4) we then get
(33)

$$
\begin{aligned}
\int_{\mathbb{R}^{n}} a(|\nabla u|) h(x)|\nabla u|^{2} \varphi^{2} \mathrm{~d} \mu & \leq \int_{\mathbb{R}^{n}}\langle(A(\nabla u(x)) \nabla(|\nabla u| \varphi)), \nabla(|\nabla u| \varphi)\rangle-f^{\prime}(u)|\nabla u|^{2} \varphi^{2} \mathrm{~d} \mu \\
& =\int_{\mathbb{R}^{n}}|\nabla u|^{2}\langle A \nabla \varphi, \nabla \varphi\rangle \mathrm{d} \mu+\int_{\{\nabla u \neq 0\}} \varphi^{2}\langle A \nabla| \nabla u|, \nabla| \nabla u| \rangle \\
& +2 \varphi|\nabla u|\langle A \nabla \varphi, \nabla| \nabla u| \rangle-f^{\prime}(u)|\nabla u|^{2} \varphi^{2} \mathrm{~d} \mu
\end{aligned}
$$

and by (32) we conclude that
(34)

$$
\begin{aligned}
\int_{\mathbb{R}^{n}} a(|\nabla u|) h(x)|\nabla u|^{2} \varphi^{2} \mathrm{~d} \mu & \leq \int_{\mathbb{R}^{n}}|\nabla u|^{2}\langle A \nabla \varphi, \nabla \varphi\rangle \mathrm{d} \mu+\int_{\{\nabla u \neq 0\}} a(|\nabla u|)\left\langle\nabla^{2} G \nabla u, \nabla u\right\rangle \varphi^{2} \mathrm{~d} \mu \\
& +\int_{\{\nabla u \neq 0\}} \varphi^{2}\left[\langle A \nabla| \nabla u|, \nabla| \nabla u| \rangle-\sum_{i=1}^{n}\left\langle A(\nabla u) \nabla u_{i}, \nabla u_{i}\right\rangle\right] \mathrm{d} \mu
\end{aligned}
$$

which is the thesis.
Remark 2.6. Letting

$$
L_{u, x}:=\left\{y \in \mathbb{R}^{n} \mid u(y)=u(x)\right\}
$$

we denote by $\nabla_{T} u$ the tangential gradient of $u$ along $L_{u, x} \cap\{\nabla u \neq 0\}$, and by $k_{1}, \ldots, k_{n-1}$ the principal curvatures of $L_{u, x} \cap\{\nabla u \neq 0\}$.

$$
\begin{equation*}
\langle A \nabla| \nabla u|, \nabla| \nabla u\left\rangle-\sum_{i=1}^{n}\left\langle A(\nabla u) \nabla u_{i}, \nabla u_{i}\right\rangle=a\left[\left.|\nabla| \nabla u\right|^{2}-\sum_{i=1}^{n}\left|\nabla u_{i}\right|^{2}\right]-a^{\prime}\right| \nabla u\left|\left|\nabla_{T}\right| \nabla u\right|^{2} \tag{35}
\end{equation*}
$$

and using (6) we get

$$
\begin{align*}
& \langle A \nabla| \nabla u|, \nabla| \nabla u\left\rangle-\sum_{i=1}^{n}\left\langle A(\nabla u) \nabla u_{i}, \nabla u_{i}\right\rangle\right.  \tag{36}\\
& =-\lambda_{1}\left|\nabla_{T}\right| \nabla u| |^{2}-a(|\nabla u|)\left(\sum_{i=1}^{n}\left|\nabla u_{i}\right|^{2}-\left|\nabla_{T}\right| \nabla u| |^{2}-\left.|\nabla| \nabla u\right|^{2}\right)
\end{align*}
$$

Notice that the quantity

$$
\sum_{i=1}^{n}\left|\nabla u_{i}\right|^{2}-\left.|\nabla| \nabla u\right|^{2}-\left|\nabla_{T}\right| \nabla u| |^{2}
$$

has a geometric interpretation, in the sense that it can be expressed in terms of the principal curvatures of level sets of $u$.

More precisely, the following formula holds (see [9, 20, 21])

$$
\begin{equation*}
\sum_{i=1}^{n}\left|\nabla u_{i}\right|^{2}-|\nabla| \nabla u| |^{2}-\left|\nabla_{T}\right| \nabla u| |^{2}=|\nabla u|^{2} \sum_{j=1}^{n-1} k_{j}^{2} \quad \text { on } L_{u, x} \cap\{\nabla u \neq 0\} \tag{37}
\end{equation*}
$$

so that (34) becomes

$$
\begin{aligned}
& \int_{\{\nabla u \neq 0\}} a(|\nabla u|) h(x)|\nabla u|^{2} \varphi^{2}+\left[\lambda_{1}\left|\nabla_{T}\right| \nabla u| |^{2}+a(|\nabla u|)|\nabla u|^{2} \sum_{j=1}^{n-1} k_{j}^{2}\right] \varphi^{2} \\
& \quad-a(|\nabla u|)\left\langle\nabla^{2} G \nabla u, \nabla u\right\rangle \varphi^{2} \mathrm{~d} \mu \\
& \leq \int_{\mathbb{R}^{n}}\langle A \nabla \varphi, \nabla \varphi\rangle|\nabla u|^{2} \mathrm{~d} \mu .
\end{aligned}
$$

Rearranging the terms, we obtain

$$
\begin{equation*}
\int_{\{\nabla u \neq 0\}} a(|\nabla u|)\left\langle\left(h(x) I-\nabla^{2} G\right) \nabla u, \nabla u\right\rangle \varphi^{2}+\left[\lambda_{1}\left|\nabla_{T}\right| \nabla u| |^{2}+a(|\nabla u|)|\nabla u|^{2} \sum_{j=1}^{n-1} k_{j}^{2}\right] \varphi^{2} \mathrm{~d} \mu \tag{38}
\end{equation*}
$$

$$
\leq \int_{\mathbb{R}^{n}}\langle A \nabla \varphi, \nabla \varphi\rangle|\nabla u|^{2} \mathrm{~d} \mu,
$$

where $I \in \operatorname{Mat}(n \times n)$ denotes the identity matrix.
Notice that from (38) we also obtain

$$
\begin{equation*}
\int_{\{\nabla u \neq 0\}} a(|\nabla u|)\left\langle\left(h(x) I-\nabla^{2} G\right) \nabla u, \nabla u\right\rangle \varphi^{2} \mathrm{~d} \mu \leq \int_{\mathbb{R}^{n}}\langle A \nabla \varphi, \nabla \varphi\rangle|\nabla u|^{2} \mathrm{~d} \mu . \tag{39}
\end{equation*}
$$

## 3. One-dimensional symmetry of solutions

In this section we will use (38) to prove several one-dimensional results for solutions to (1), following the approach introduced in [5] and then developed in [9]. Notice that, more recently, a similar approach has also been used to handle semilinear equations in Riemannian and subriemannian spaces (see $[6,7,8,12,13,19]$ ) and also to study problems involving the Ornstein-Uhlenbeck operator [2], as well as semilinear equations with unbounded drift [3].

The following Lemma is proved in [9, 13].
Lemma 3.1. Let $g \in L_{\text {loc }}^{\infty}\left(\mathbb{R}^{n},[0,+\infty)\right)$ and let $q>0$. Let also, for any $\tau>0$,

$$
\begin{equation*}
\eta(\tau):=\int_{B_{\tau}} g(x) \mathrm{d} x . \tag{40}
\end{equation*}
$$

Then, for any $0<r<R$,

$$
\begin{equation*}
\int_{B_{R} \backslash B_{r}} \frac{g(x)}{|x|^{q}} \mathrm{~d} x \leq q \int_{r}^{R} \frac{\eta(\tau)}{|\tau|^{q+1}} \mathrm{~d} \tau+\frac{1}{R^{q}} \eta(R) \tag{41}
\end{equation*}
$$

## Proof of Theorem 1.

Let us fix $R>0$ (to be taken appropriately large in what follows) and $x \in \mathbb{R}^{n}$ and let us define

$$
\varphi(x):= \begin{cases}1 & \text { if } x \in B_{\sqrt{R}}  \tag{42}\\ 2 \frac{\log (R /|x|)}{\log (R)} & \text { if } \quad x \in B_{R} \backslash B_{\sqrt{R}} \\ 0 & \text { if } x \in \mathbb{R}^{n} \backslash B_{R}\end{cases}
$$

where $B_{R}:=\left\{y \in \mathbb{R}^{n}| | y \mid<R\right\}$. Obviously $\varphi \in \operatorname{Lip}\left(\mathbb{R}^{n}\right)$ and

$$
|\nabla \varphi(x)| \leq C_{2} \frac{\chi_{\sqrt{R}, R}(x)}{\log (R)|x|}
$$

for suitable $C_{2}>0$. Hence for every $R>e$, (38) together with $h \geq \lambda_{G}$ yields

$$
\begin{equation*}
\int_{\{\nabla u \neq 0\} \cap \bar{B}_{R}}\left[\left.\lambda_{1}\left|\nabla_{T}\right| \nabla u\right|^{2}+a(|\nabla u|)|\nabla u|^{2} \sum_{j=1}^{n-1} k_{j}^{2}\right] \varphi^{2} \mathrm{~d} \mu \leq \int_{\mathbb{R}^{n}}\langle A(\nabla u) \nabla \varphi, \nabla \varphi\rangle|\nabla u|^{2} \mathrm{~d} \mu \tag{43}
\end{equation*}
$$

therefore, by (12)

$$
\begin{align*}
\int_{\{\nabla u \neq 0\} \cap \bar{B}_{R}}\left[\left.\lambda_{1}\left|\nabla_{T}\right| \nabla u\right|^{2}+a(|\nabla u|)|\nabla u|^{2} \sum_{j=1}^{n-1} k_{j}^{2}\right] \varphi^{2} \mathrm{~d} \mu & \leq(1+C) \int_{\mathbb{R}^{n}} a(|\nabla u|)|\nabla \varphi|^{2}|\nabla u|^{2} \mathrm{~d} \mu  \tag{44}\\
& \leq \frac{(1+C) C_{2}^{2}}{\log (R)^{2}} \int_{B_{R} \backslash B_{\sqrt{R}}} \frac{a(|\nabla u|)|\nabla u|^{2}}{|x|^{2}} \mathrm{~d} \mu
\end{align*}
$$

Applying Lemma 3.1 with $g=a(|\nabla u|)|\nabla u|^{2} e^{G}$ and $q=2$, and recalling that

$$
\int_{B_{R}} a(|\nabla u|)|\nabla u|^{2} \mathrm{~d} \mu \leq C_{0} R^{2}
$$

for $R$ large, we obtain

$$
\begin{align*}
\int_{\{\nabla u \neq 0\} \cap \bar{B}_{R}}\left[\left.\lambda_{1}\left|\nabla_{T}\right| \nabla u\right|^{2}+a(|\nabla u|)|\nabla u|^{2} \sum_{j=1}^{n-1} k_{j}^{2}\right] \varphi^{2} \mathrm{~d} \mu & \leq \frac{(1+C) C_{0} C_{2}^{2}}{\log (R)^{2}}\left[2 \int_{\sqrt{R}}^{R} \frac{1}{|\tau|} \mathrm{d} \tau+1\right]  \tag{45}\\
& \leq 2 \frac{(1+C) C_{0} C_{2}^{2}}{\log (R)}
\end{align*}
$$

Therefore, sending $R \rightarrow+\infty$ in (45) we get

$$
\begin{equation*}
k_{j}(x)=0 \quad \text { and } \quad\left|\nabla_{T}\right| \nabla u \|(x)=0 \tag{46}
\end{equation*}
$$

for every $j=1, \ldots, n-1$ and every $x \in\{\nabla u \neq 0\}$. From this and Lemma 2.11 in [9] we get the one-dimensional symmetry of $u$.

Let us now suppose $n=2$ and $a(|\nabla u|)|\nabla u|^{2} e^{G} \in L^{\infty}\left(\mathbb{R}^{2}\right)$. Taking in (38) the following test function

$$
\begin{equation*}
\varphi(x)=\max \left[0, \min \left(1, \frac{\ln R^{2}-\ln |x|}{\ln R}\right)\right] \tag{47}
\end{equation*}
$$

recalling that $h \geq \lambda_{G}$ and following [9, Cor. 2.6], we then obtain
$\int_{\{\nabla u \neq 0\} \cap \bar{B}_{R}}\left[\left.\lambda_{1}\left|\nabla_{T}\right| \nabla u\right|^{2}+a(|\nabla u|)|\nabla u|^{2} \sum_{j=1}^{n-1} k_{j}^{2}\right] \varphi^{2} \mathrm{~d} \mu \leq C^{\prime} \int_{B_{R^{2}} \backslash B_{R}} \frac{a(|\nabla u|(x))}{|x|^{2}(\ln R)^{2}}|\nabla u|^{2} e^{G(x)} \mathrm{d} x$
for some constant $C^{\prime}>0$. When $R \rightarrow+\infty$, since $a(|\nabla u|)|\nabla u|^{2} e^{G(x)}$ is bounded, the r.h.s. term of the previous inequality goes to zero, and we conclude again that $u$ is onedimensional.

Assume now that $u$ is not constant. If we take in (39) the same test functions as above, we get

$$
\int_{\mathbb{R}^{n}} a(|\nabla u|)\left\langle\left(h(x) \mathrm{I}_{n}-\nabla^{2} G(x)\right) \nabla u, \nabla u\right\rangle \mathrm{d} \mu(x)=0 .
$$

Using the fact that $u(x)=u_{0}(\langle\omega, x\rangle)$ and $a(t)>0$ we obtain that $\left\langle\left(h(x) \mathrm{I}_{n}-\nabla^{2} G(x)\right) \omega, \omega\right\rangle=$ 0 for all $x$ such that $u_{0}^{\prime}(\langle\omega, x\rangle) \neq 0$. Since $u$ is not constant and is a solution to the elliptic equation (1), the set of points such that $u_{0}^{\prime}(\langle\omega, x\rangle)=0$ has zero measure, so, by the regularity of $G$ we conclude that

$$
\left\langle\left(h(x) \mathrm{I}_{n}-\nabla^{2} G(x)\right) \omega, \omega\right\rangle=0 \quad \forall x \in \mathbb{R}^{n}
$$

which gives (14) and (15).

As pointed out in [3], a Liouville type result follows from Theorem 1.
Corollary 3.2. Let $G, h, u$ satisfy the assumptions in Theorem 1. Assume further that $h \in C^{0}\left(\mathbb{R}^{n}\right)$ and $h(x)>\lambda_{G}(x)$ for some $x \in \mathbb{R}^{n}$. Then $u$ is constant. In particular, if $u$ is a stable solution, that is $h \equiv 0$, and $\lambda_{G}(x)<0$ for some $x \in \mathbb{R}^{n}$, then $u$ is constant.

In the following lemma we give a sufficient condition for a solution $u$ to satisfy condition (a) in Theorem 1.

Lemma 3.3. Let $u$ be a weak solution to (1). Then, for each $\varphi \in C_{c}^{1}\left(\mathbb{R}^{n}\right)$,

$$
\begin{equation*}
\int_{\mathbb{R}^{n}} a(|\nabla u|)|\nabla u|^{2} \varphi \mathrm{~d} \mu=-\int_{\mathbb{R}^{n}} a(|\nabla u|)\langle\nabla u, \nabla \varphi\rangle u \mathrm{~d} \mu+\int_{\mathbb{R}^{n}} f(u) u \varphi \mathrm{~d} \mu \tag{48}
\end{equation*}
$$

In particular, if $t \rightarrow t a(t) \in L^{\infty}((0,+\infty))$, $u \in L^{\infty}\left(\mathbb{R}^{n}\right)$ and $\mu\left(\mathbb{R}^{n}\right)<+\infty$ then there exists $C>0$ such that

$$
\begin{equation*}
\int_{\mathbb{R}^{n}} a(|\nabla u|)|\nabla u|^{2} \mathrm{~d} \mu \leq C \tag{49}
\end{equation*}
$$

Proof. Clearly (48) follows by taking $u \varphi$ as test function in (8). Let us show (49). For every $R>1$ let $\Phi_{R} \in C^{\infty}(\mathbb{R})$ be such that $\Phi_{R}(t)=1$ if $t \leq R, \Phi_{R}(t)=0$ if $t \geq R+1$ and
$\Phi_{R}^{\prime}(t) \leq 3$ for $t \in[R, R+1]$, and define $\varphi(x):=\Phi_{R}(|x|)$. Then $|\nabla \varphi(x)| \leq\left|\Phi_{R}^{\prime}(|x|)\right| \leq 3$, and (48) yields

$$
\int_{B_{R}} a(|\nabla u|)|\nabla u|^{2} \mathrm{~d} \mu \leq 3 \int_{B_{R+1} \backslash B_{R}} a(|\nabla u|)|\nabla u||u| \mathrm{d} \mu+\int_{B_{R+1}}|f(u)||u| \mathrm{d} \mu \leq C
$$

which gives (49) by letting $R \rightarrow+\infty$.

In the rest of the section we fix $G(x)=-|x|^{2} / 2$. We start with a result which follows directly from Lemma 2.3.

Lemma 3.4. Let $G(x):=-|x|^{2} / 2$ and assume that $u$ is a monotone weak solution to (1), i.e. there exists $i \in\{1, \ldots, n\}$ such that

$$
\begin{equation*}
\partial_{i} u(x)>0 \quad \forall x \in \mathbb{R}^{n} \tag{50}
\end{equation*}
$$

then $u \in C^{2}\left(\mathbb{R}^{n}\right)$ and $u$ is $(-1)-$ stable.
Proof of Theorem 2. We start observing that $u$ is $(-1)-$ stable by Lemma 2.3. Since $\nabla^{2} G(x)=-I d$ we have

$$
\begin{equation*}
-1=h(x)=\lambda_{G}(x)=-1 \tag{51}
\end{equation*}
$$

If $a(t)=t^{p-2}$ for some $p>1$ then

$$
\begin{equation*}
\lambda_{1}(t)=(p-1) t^{p-2}=(p-1) a(t) \quad \forall t>0 \tag{52}
\end{equation*}
$$

and the conclusion follows by Theorem 1. If $a(t)=\left(1+t^{q}\right)^{-\frac{1}{q}}$ with $q>1$ then

$$
\begin{align*}
& \lambda_{1}(t)=\left(1+t^{q}\right)^{-\frac{1}{q}}-\left(1+t^{q}\right)^{-\frac{q+1}{q}} t^{q} \leq a(t) \quad \forall t>0  \tag{53}\\
& t a(t) \leq 1 \quad \forall t>0 \tag{54}
\end{align*}
$$

By Lemma 3.3 and (54) there exists $C>0$ such that

$$
\begin{equation*}
\int_{\mathbb{R}^{n}} a(|\nabla u|)|\nabla u|^{2} \mathrm{~d} \mu \leq C \tag{55}
\end{equation*}
$$

Notice that, if $a(t)=1$ for every $t>0$, by Theorem [17, Theorem 4.1] we have $u \in$ $H^{2}\left(\mathbb{R}^{n}, \mu\right)$, so that (55) holds in this case, too. The conclusion follows by (53), (55) and Theorem 1.

## 4. Solutions with Morse index bounded by the euclidean dimension

In this section we will focus on the Ornstein-Uhlenbeck operator. More precisely, we will consider weak solutions $u \in H^{1}\left(\mathbb{R}^{n}, \mu\right) \cap L^{\infty}\left(\mathbb{R}^{n}\right)$ to

$$
\begin{equation*}
\Delta u-\langle x, \nabla u\rangle+f(u)=0 \tag{56}
\end{equation*}
$$

where $f \in C^{1}(\mathbb{R})$, and we will prove some new symmetry results for solutions with Morse index $k \leq n$. We recall that, by Theorem [17, Theorem 4.1], bounded weak solutions to (56) satisfy $u \in H^{2}\left(\mathbb{R}^{n}, \mu\right) \cap L^{\infty}\left(\mathbb{R}^{n}\right)$.

Definition 4.1. A bounded weak solution $u$ to the Ornstein-Uhlenbeck operator has Morse index $k \in \mathbb{N}$ if $k$ is the maximal dimension of a subspace $X$ of $H^{1}\left(\mathbb{R}^{n}, \mu\right)$ such that

$$
\begin{equation*}
Q_{u}(\varphi):=\int_{\mathbb{R}^{n}}|\nabla \varphi|^{2}-f^{\prime}(u) \varphi^{2} \mathrm{~d} \mu<0 \quad \forall \varphi \in X \backslash\{0\} \tag{57}
\end{equation*}
$$

Remark 4.2. Let $u$ be a bounded solution to (56) and let $L: H^{2}\left(\mathbb{R}^{n}, \mu\right) \rightarrow L^{2}\left(\mathbb{R}^{n}, \mu\right)$ be the linear operator defined as

$$
\begin{equation*}
L(v):=-\Delta v+\langle\nabla v, x\rangle-f^{\prime}(u) v \tag{58}
\end{equation*}
$$

Notice that $L$ is self-adjoint in $L^{2}\left(\mathbb{R}^{n}, \mu\right)$ with compact inverse, so that by the Spectral Theorem [15] there exists an orthonormal basis of $L^{2}\left(\mathbb{R}^{n}, \mu\right)$ consisting of eigenvectors of $L$, and each eigenvalue of $L$ is real. Then, $u$ has Morse index $k$ if and only if $L$ has exactly $k$ strictly negative eigenvalues, repeated according to their geometric multiplicity (see for instance [17, Theorem 4.1]).

The following Proposition is proved in [2, Lemma 3.2].
Proposition 4.3. Let $u$ be a bounded weak solution to (56). If for some $i=1, \ldots, n$, $u_{i}$ is not identically zero then it is an eigenfunction of $L$ with eigenvalue -1 , i.e.

$$
\begin{equation*}
\int_{\mathbb{R}^{n}}\left\langle\nabla u_{i}, \nabla \varphi\right\rangle+u_{i} \varphi-f^{\prime}(u) u_{i} \varphi \mathrm{~d} \mu=0, \quad \forall \varphi \in H^{1}\left(\mathbb{R}^{n}, \mu\right) \tag{59}
\end{equation*}
$$

We are now in a position to prove Theorem 3.

## Proof of Theorem 3.

By [17, Theorem 4.1] every bounded weak solution to (56) belongs to $H^{2}\left(\mathbb{R}^{n}, \mu\right)$, hence $u_{i} \in H^{1}\left(\mathbb{R}^{n}, \mu\right)$ for all $i=1, \ldots, n$. Therefore, using (59) with $u_{i}$ as test function we obtain

$$
\begin{equation*}
Q_{u}\left(u_{i}\right)=\int_{\mathbb{R}^{n}}\left|\nabla u_{i}\right|^{2}-f^{\prime}(u) u_{i}^{2} \mathrm{~d} \mu=-\int_{\mathbb{R}^{n}} u_{i}^{2} \leq 0, \quad \forall i=1, \ldots, n \tag{60}
\end{equation*}
$$

In particular

$$
\begin{equation*}
Q_{u}\left(u_{i}\right)<0 \tag{61}
\end{equation*}
$$

for every $i=1, \ldots, n$ such that $u_{i}$ is not identically zero. Let $L$ be the operator defined in (58). If $k=0$ then $u$ is stable, hence it is constant by Corollary 3.2. If $k=1$ then, by Remark 4.2 and Proposition 4.3, it follows that -1 is the smallest eigenvalue of $L$, that is

$$
\begin{equation*}
\inf _{\varphi \in H^{1}\left(\mathbb{R}^{n}, \mu\right),\|\varphi\|_{L^{2}\left(\mathbb{R}^{n}, \mu\right)}=1}\left(\int_{\mathbb{R}^{n}}|\nabla \varphi|^{2}-f^{\prime}(u) \varphi^{2} \mathrm{~d} \mu\right)=-1 \tag{62}
\end{equation*}
$$

Using (62) it follows that $u$ is $(-1)$-stable and therefore, by Theorem 1, $u$ is onedimensional. Assume now $2 \leq k \leq n$ and define $S:=\left\{i \in\{1, \ldots, n\} \mid u_{i}(x) \neq\right.$ 0 , for some $\left.x \in \mathbb{R}^{n}\right\}$ and $X:=\operatorname{span}_{i \in S}\left\{u_{i}\right\} \subset H^{1}\left(\mathbb{R}^{n}, \mu\right)$. Clearly,

$$
\begin{equation*}
Q_{u}(v)<0 \quad \forall v \in X \backslash\{0\} \tag{63}
\end{equation*}
$$

therefore, by Definition 4.1, $X$ has dimension less or equal than $k$, i.e. there exists $I \subset S$ with $|I| \geq|S|-k$ such that $\left\{u_{i}\right\}_{i \in I}$ are linearly dependent [15]. This means that, up to an orthogonal change of variables, $u$ depends on at most $k$ variables. Let us assume by contradiction that $u$ is a function of exactly $k$ variables. We claim that -1 is the smallest
eigenvalue of $L$, as before. Indeed, if this is not the case, then there exist $\lambda<-1$ and $v \in H^{1}\left(\mathbb{R}^{n}, \mu\right)$, with $v \not \equiv 0$, such that $L(v)=\lambda v$. Therefore, by the linear independence of eigenvectors associated to different eigenvalues, it follows that $Y:=\operatorname{span}\left\{u_{i}, v\right\}$ has dimension equal to $k+1$ and $Q_{u}(w)<0$ for every $w \in Y \backslash\{0\}$ which is in contradiction with the fact that $u$ has Morse index $k$. This proves that $u$ is a function of at most $(k-1)$ variables, as claimed.

## References

[1] Bogachev, V.I., Gaussian measures. Mathematical Surveys and Monographs, vol. 62, American Mathematical Society, Providence, RI, (1998).
[2] Cesaroni, A., Novaga, M., Valdinoci, E.: A simmetry result for the Ornstein-Uhlenbeck operator, Discrete Contin. Dyn. Syst. A, 34, no 6, 2451-2467 (2014).
[3] Cesaroni, A., Novaga, M., Pinamonti, A.: One-dimensional symmetry for semilinear equations with unbounded drift, Commun. Pure Appl. Anal. 12, no 5, 2203-2211 (2013).
[4] Da Prato, G., Lunardi, A.: Elliptic operators with unbounded drift coefficients and Neumann boundary condition, J. Differential Equations 198, 35-52 (2004).
[5] Farina,A.: Propriétés qualitatives de solutions d'équations et systèmes d'équations non-linéaires, Habilitation à diriger des recherches, Paris VI, (2002).
[6] Farina, A., Mari, L., Valdinoci, E.: Splitting theorems, symmetry results and overdetermined problems for Riemannian manifolds, in Comm. in PDE, 38, no. 10, (2013).
[7] Farina, A., Sire, Y., Valdinoci, E.: Stable solutions of elliptic equations on Riemannian manifolds, to appear in J. Geom. Anal. , 23, no. 3, 11581172 (2013).
[8] Farina, A., Sire, Y., Valdinoci, E.: Stable solutions of elliptic equations on Riemannian manifolds with Euclidean coverings, Proc. Amer. Math. Soc. 140 , no. 3, 927-930 (2012).
[9] Farina, A., Sciunzi, B., Valdinoci, E.: Bernstein and De Giorgi type problems: new results via a geometric approach, Ann. Sc. Norm. Super. Pisa Cl. Sci. (5) 7, 741-791 (2008).
[10] Farina, A., Sciunzi, B., Valdinoci, E.: On a Poincaré type formula for solutions of singular and degenerate elliptic equations, Manuscripta math. 132, 335-342 (2010).
[11] Farina, A., Valdinoci, E.: The state of the art for a conjecture of De Giorgi and related problems. In: Du, Y., Ishii, H., Lin, W.-Y. (eds.), Recent Progress on Reaction Diffusion System and Viscosity Solutions. Series on Advances in Mathematics for Applied Sciences, 372 World Scientific, Singapore (2008).
[12] Ferrari, F., Pinamonti, A.: Nonexistence results for semilinear equations in Carnot groups, Analysis and Geometry in Metric Spaces, 130-146 (2013).
[13] Ferrari, F., Valdinoci, E.: A geometric inequality in the Heisenberg group and its applications to stable solutions of semilinear problems, Math. Annalen 343, 351-370 (2009).
[14] Hussey, C.: Classification and Analysis of Low Index Mean Curvature Flow Self-Shrinkers, PhD Thesis, Johns Hopkins University, Baltimore, USA (2012).
[15] Kato, T.: Perturbation Theory for Linear Operators, Springer-Verlag, (1980).
[16] Ladyzhenskaya, O., Uraltseva, N.: Linear and Quasilinear Elliptic Equations, Academic Press, New York, (1968).
[17] Lunardi, A.: On the Ornstein-Uhlenbeck operator in $L^{2}$ spaces with respect to invariant measures. Trans. Amer. Math. Soc., 349, 155-169 (1997).
[18] Lieb, H. H., Loss,M.: Analysis, vol. 14 of Graduate Studies in Mathematics, AMS, Providence, RI (1997).
[19] Pinamonti, A., Valdinoci, E.: A geometric inequality for stable solutions of semilinear elliptic problems in the Engel group, Ann. Acad. Sci. Fenn. Math. ,37, 357-373 (2012).
[20] Sternberg, P., Zumbrun, K.: A Poincaré inequality with applications to volume-constrained areaminimizing surfaces, J. Reine Angew. Math. 503, 63-85 (1998).
[21] Sternberg, P., Zumbrun, K.: Connectivity of phase boundaries in strictly convex domains, Arch. Ration. Mech. Anal. 141, 375-400 (1998).
[22] Tolksdorff, P.: Regularity for a more general class of quasilinear elliptic equations, J. Diff. Equ. 51, 126-160 (1984).
[23] Hutchinson, J., Tonegawa, Y.: Convergence of phase interfaces in the van der Waals-Cahn-Hilliard theory, Calc. Var. Partial Differential Equations 10, 49-84 (2000).

LAMFA-CNRS UMR 7352, Université de Picardie Jules Verne, Faculté des Sciences, 33, Rue Saint-Leu, 80039, Amiens, France

Institut Camille Jordan, CNRS UMR 5208, Université Claude Bernard, Lyon I, Villeurbanne, France

E-mail address: alberto.farina@u-picardie.fr
Dipartimento di Matematica, Università di Padova, Via Trieste 63, Padova, Italy
E-mail address: pinamonti@science.unitn.it
Dipartimento di Matematica, Università di Pisa, Largo Bruno Pontecorvo 5, Pisa, Italy
E-mail address: novaga@dm.unipi.it


[^0]:    A.F. and M.N. are supported by the ERC grant EPSILON - Elliptic Pde's and Symmetry of Interfaces and Layers for Odd Nonlinearities. M.N. and A.P. acknowledge partial support by the CaRiPaRo project Nonlinear Partial Differential Equations: models, analysis, and control-theoretic problems.
    ${ }^{1}$ One could consider functions $f$ which are only locally lipschitz continuous, as in [9]. To avoid inessential technicalities, we do not treat this case here.

[^1]:    ${ }^{2}$ cfr. also [9, footnote 1 at p. 742 and footnote 2 at page 743].

