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## *$L^p$ -Stability for the Strong Solutions of the Navier-Stokes Equations in the Whole Space*

H. BEIRÃO DA VEIGA & P. SECCHI

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### Introduction

Consider the initial value problem for the non-stationary Navier-Stokes equations in the whole space  $R^3$

$$\begin{aligned} v' + (v \cdot \nabla) v - \Delta v + \nabla \pi &= 0 & \text{in } Q_T \equiv ]0, T[ \times R^3, \\ \operatorname{div} v &= 0 & \text{in } Q_T, \\ v|_{t=0} &= a & \text{in } R^3, \\ \lim_{|x| \rightarrow \infty} v(t, x) &= 0 & \text{for } t \in ]0, T[, \end{aligned} \quad (1)$$

where

$$T \in ]0, \infty], \quad v' = \frac{\partial v}{\partial t} \quad \text{and} \quad (v \cdot \nabla) v = \sum_{i=1}^3 v_i \frac{\partial v}{\partial x_i}.$$

The given initial velocity  $a(x)$  satisfies  $\operatorname{div} a = 0$  in  $R^3$ . Moreover, the pressure  $\pi$  is determined by the condition  $\lim_{|x| \rightarrow \infty} \pi(t, x) = 0$  for  $t \in ]0, T[$ . By a solution of problem (1), we mean a divergence free vector  $v(t, x) \in L^q(0, T; L^r)$  for some  $q, r$  with  $q, r \geq 2$ , such that

$$\int_0^T \int [v \cdot \varphi' + (v \cdot \nabla) \varphi \cdot v + v \cdot \Delta \varphi] dx dt = - \int a \varphi|_{t=0} dx,$$

for every regular divergence free vector field  $\varphi(t, x)$ , with compact support with respect to the space variables and such that  $\varphi(T, x) = 0$ . We set

$$\begin{aligned} L^p &= L^p(R^3), \quad \| \cdot \|_p = \| \cdot \|_{L^p(R^3)}, \\ N_p(v) &= \int_{R^3} |\nabla v|^2 |v|^{p-2} dx. \end{aligned}$$

Other notations are standard, or will be introduced in the sequel. Let  $p > 3$  and  $a_1 \in L^1 \cap L^{p+2}$ ,  $\operatorname{div} a_1 = 0$ . Assume that there exists a global solution

$v_1 \in L^\infty(0, +\infty; L^{p+2})$  of problem (1), with initial velocity  $a_1$  and pressure  $\pi_1$ . This solution is strong and unique<sup>1</sup>. We prove the following stability result:

**Theorem A.** *Assume that the above conditions hold and let  $a_2 \in L^1 \cap L^p$ , be such that  $\operatorname{div} a_2 = 0$ . Then, there exists a positive constant  $y_0$  such that, if*

$$|a_1 - a_2|_p < y_0, \quad (2)$$

there exists a unique solution  $v_2 \in C([0, +\infty); L^p)$  of (1) with initial data  $a_2$ . This solution satisfies the estimate

$$|v_1(t) - v_2(t)|_p \leq C(1+t)^{-\frac{3}{4}}. \quad (3)$$

The constants  $y_0$  and  $C$  depend on  $p$ , on the  $L^1$  and  $L^2$  norms of the initial data  $a_1$  and  $a_2$ , and on the  $L^\infty(0, +\infty; L^{p+2})$  norm of  $v_1$ . In particular, by considering initial data  $a_2$  such that

$$|a_2|_1 \leq |a_1|_1 + k_1, \quad |a_2|_2 \leq |a_1|_2 + k_2,$$

where  $k_1$  and  $k_2$  are any positive constants,  $y_0$  and  $C$  depend only on  $k_1, k_2$  and on the norms  $|a_1|_1, |a_1|_2$  and  $\|v_1\|_{L^\infty(0, +\infty; L^{p+2})}$  of the unperturbed solution  $v_1$ . The local existence and uniqueness of a strongly continuous solution  $v_2(t)$  with values in  $L^2 \cap L^p$  is well known. The bound (3) guarantees the global existence of  $v_2(t)$ . See the note added in proof.

The proof of theorem A follows the method introduced in reference [1] in order to study the asymptotic behavior of the solutions of system (1).

**Proof of Theorem A.** The difference  $w = v_2 - v_1$ , satisfies the following system:

$$w' + (v_2 \cdot \nabla) w + (w \cdot \nabla) v_1 - \Delta w + \nabla P = 0 \quad \text{in } Q_T, \quad (4)$$

$$\operatorname{div} w = 0 \quad \text{in } Q_T,$$

$$w|_{t=0} = \alpha \quad \text{in } R^3,$$

where  $P = \pi_2 - \pi_1$  and  $\alpha = a_2 - a_1$ . Multiply both sides of equation (4) by  $|w|^{p-2} w$  and integrate over  $R^3$ . After suitable integrations by parts we obtain

$$\begin{aligned} & \frac{1}{p} \frac{d}{dt} |w|_p^p + N_p(w) + 4 \frac{p-2}{p^2} \int |\nabla|w|^{p/2}|^2 \\ &= - \int (v_2 \cdot \nabla) w \cdot |w|^{p-2} w - \int (w \cdot \nabla) v_1 \cdot |w|^{p-2} w - \int \nabla P \cdot |w|^{p-2} w. \end{aligned}$$

The first term on the right-hand side is zero since  $v_2$  is divergence free. By integrating by parts the other two terms we get

$$\frac{1}{p} \frac{d}{dt} |w|_p^p + N_p(w) \leq (p-1) \int |w|^{p-1} |\nabla w| |v_1| + (p-2) \int |P| |w|^{p-2} |\nabla w|. \quad (5)$$

<sup>1</sup> We refer the reader to the results proved in [2]. See also [5], and references there.

Consider the first integral on the right-hand side of (5). By Hölder's and Young's inequalities one has

$$\begin{aligned} (p-1) \int |w|^{p-1} |\nabla w| |v_1| &\leq (p-1) N_p(w)^{1/2} (\int |w|^p |v_1|^2)^{1/2} \\ &\leq \frac{1}{8} N_p(w) + 2(p-1)^2 \int |w|^p |v_1|^2 \\ &\leq \frac{1}{8} N_p(w) + 2(p-1)^2 |w|_{p+2}^p |v_1|_{p+2}^2. \end{aligned} \quad (6)$$

On the other hand, one can prove the following inequality (see [1], equation (1.14)):

$$|w|_{p+2}^p \leq C N_p(w)^{\frac{3}{p+2}} |w|_p^{\frac{p(p-1)}{p+2}}; \quad (7)$$

hence, from (6), one obtains

$$(p-1) \int |w|^{p-1} |\nabla w| |v_1| \leq \frac{1}{4} N_p(w) + C |w|_p^p |v_1|_{\frac{p-1}{p+2}}^{\frac{2(p+2)}{p-1}}. \quad (8)$$

Consider now the second integral on the right-hand side of (5). By Hölder's and Young's inequalities we have

$$\begin{aligned} (p-2) \int |P| |w|^{p-2} |\nabla w| &\leq (p-2) (\int |P|^2 |w|^{p-2})^{1/2} N_p(w)^{1/2} \\ &\leq 2(p-2)^2 \int |P|^2 |w|^{p-2} + \frac{1}{8} N_p(w) \\ &\leq 2(p-2)^2 |P|_{\frac{p+2}{2}}^2 |w|_{\frac{p+2}{2}}^{p-2} + \frac{1}{8} N_p(w). \end{aligned} \quad (9)$$

To estimate  $P$ , we take the divergence of (4) and obtain

$$-\Delta P = \sum_{i,j} \frac{\partial^2}{\partial x_i \partial x_j} w'(v_1^i + v_2^j) = \sum_{i,j} \frac{\partial^2}{\partial x_i \partial x_j} [w'(2v_1^i + w^j)].$$

From the Calderon-Zygmund inequality one has

$$|P|_{\frac{p+2}{2}} \leq C \sum_{i,j} |w'(2v_1^i + w^j)|_{\frac{p+2}{2}};$$

then by Hölder's inequality

$$|P|_{\frac{p+2}{2}}^2 \leq C |w|_{\frac{p+2}{2}}^2 (|v_1|_{\frac{p+2}{2}}^2 + |w|_{\frac{p+2}{2}}^2).$$

By introducing this last inequality in (9) and by using inequality (7), we get

$$\begin{aligned} (p-2) \int |P| |w|^{p-2} |\nabla w| &\leq C |w|_{\frac{p+2}{2}}^p (|v_1|_{\frac{p+2}{2}}^2 + |w|_{\frac{p+2}{2}}^2) + \frac{1}{8} N_p(w) \\ &\leq C N_p(w)^{\frac{3}{p+2}} |w|_p^{\frac{p(p-1)}{p+2}} |v_1|_{\frac{p+2}{2}}^2 + C N_p(w)^{\frac{3}{p}} |w|_p^{p-1} + \frac{1}{8} N_p(w) \\ &\leq \frac{1}{4} N_p(w) + C |w|_p^p |v_1|_{\frac{p+2}{2}}^{\frac{2(p+2)}{p-1}} + C |w|_p^{\frac{p(p-1)}{p-3}}. \end{aligned} \quad (10)$$

Hence, by using inequalities (8) and (10), we get from (5)

$$\frac{1}{p} \frac{d}{dt} |w|_p^p + \frac{1}{2} N_p(w) \leq C |w|_p^p |v_1|_{\frac{p+2}{2}}^{\frac{2(p+2)}{p-1}} + C |w|_p^{\frac{p(p-1)}{p-3}}. \quad (11)$$

On the other hand, one can prove the following Sobolev type inequality (see [1], equation (3.2))

$$N_p(w) \geq C |w|_{3p}^p.$$

By interpolation, one has

$$|w|_p \leq |w|_2^{\frac{4}{3p-2}} |w|_{3p}^{\frac{3(p-2)}{3p-2}}.$$

Hence

$$N_p(w) \geq C |w|_2^{-\beta} |w|_p^{p+\beta}, \quad (12)$$

where  $\beta = 4p/3(p-2)$ . On the other hand, by a result proved in reference [3] (see also [4]) on the  $L^2$ -decay of the solutions of the Navier-Stokes equations, one has

$$|w(t)|_2 \leq |v_1(t)|_2 + |v_2(t)|_2 \leq C(t+1)^{-3/4}, \quad (13)$$

where  $C$  depends only on the  $L^1$  and  $L^2$ -norms of the initial velocities. Then, from (12) and (13), we obtain

$$N_p(w) \geq C(t+1)^{3\beta/4} |w|_p^{p+\beta}. \quad (14)$$

Hence, from (11) and (14), we have

$$\frac{1}{p} \frac{d}{dt} |w|_p^p + C(t+1)^{3\beta/4} |w|_p^{p+\beta} \leq C |w|_p^p |v_1|_{p+2}^{\frac{2(p+2)}{p-1}} + C |w|_p^{\frac{p(p-1)}{p-3}},$$

from which we obtain, since  $v_1$  is bounded in  $L^{p+2}$  uniformly in time,

$$\frac{d}{dt} |w|_p + C_1(t+1)^{3\beta/4} |w|_p^{\beta+1} \leq C_2 |w|_p + C_3 |w|_p^{1+\beta+\gamma}, \quad (15)$$

where  $\gamma = 2p^2/3(p-2)(p-3)$ . In (15),  $C_1$  depends on  $p$  and on the  $L^1$  and  $L^2$ -norms of the initial velocities,  $C_2$  depends on  $p$  and  $\|v_1\|_{L^\infty(0,T;L^{p+2})}$ ,  $C_3$  depends only on  $p$ . Consider now the corresponding ordinary differential equation

$$\begin{aligned} y'(t) + C_1(t+1)^{3\beta/4} (y(t))^{\beta+1} &= C_2 y(t) + C_3 (y(t))^{1+\beta+\gamma}, \\ y(0) &= |\alpha|_p. \end{aligned} \quad (16)$$

We prove now that, if  $|\alpha|_p$  is sufficiently small, then  $y(t) \leq C(t+1)^{-3/4}$ . By comparison theorems for ordinary differential equations it will follow that  $|w(t)|_p \leq y(t)$ ; hence (3) holds. Let  $t_0 \in ]0, +\infty[$  be such that

$$t_0 > \left( \frac{C_2 + C_3}{C_1} \right)^{4/3\beta} - 1. \quad (17)$$

By the continuous dependence on the initial data of the solution of (16), one can find  $y_0 > 0$  (depending on  $p$  and on  $C_i$ ,  $i = 1, 2, 3$ ) sufficiently small that, if  $|\alpha|_p \leq y_0$ , then  $y(t) < 1$  for each  $t \in [0, t_0]$ . Moreover, if there exists  $t \geq t_0$  such that  $y(t) = 1$ , then from (16) and (17) one has

$$\begin{aligned} y'(t) &= -C_1(t+1)^{3\beta/4} + C_2 + C_3 \\ &\leq -C_1(t_0+1)^{3\beta/4} + C_2 + C_3 < 0. \end{aligned}$$

This implies  $y(t) \leq 1$ , for any  $t \geq 0$ . From (16), we then obtain  $y(t) \leq z(t)$  for any  $t \geq 0$ , where  $z(t)$  is the solution of

$$\begin{aligned} z'(t) + C_1(t+1)^{3\beta/4} (z(t))^{\beta+1} &= (C_2 + C_3) z(t), \\ z(0) &= |\alpha|_p. \end{aligned} \quad (18)$$

Equation (18) is of Bernoulli type and its solution is given by

$$z(t) = e^{(C_2+C_3)t} \left[ |\alpha|_p^{-\beta} + \int_0^t e^{\beta(C_2+C_3)s} \beta C_1 (s+1)^{3\beta/4} ds \right]^{-\frac{1}{\beta}}.$$

Hence

$$z(t)^\beta (1+t)^{3\beta/4} \leq (1+t)^{3\beta/4} e^{\beta(C_2+C_3)t} \left[ y_0^{-\beta} + \beta C_1 \int_0^t e^{\beta(C_2+C_3)s} (1+s)^{3\beta/4} ds \right]^{-1}.$$

By the l'Hôpital theorem one easily shows that the right-hand side of the above inequality converges to  $(C_2 + C_3)/C_1$  as  $t \rightarrow +\infty$ . Since it is equal to  $y_0^\beta$  for  $t = 0$ , it is bounded in the interval  $[0, +\infty)$  by a constant  $C$  (which depends only on  $C_1, C_2, C_3$  and  $p$ ).

**Note added in proof.** We point out that both  $v_1$  and  $v_2$  (hence  $v_1 - v_2$ ) must decay like  $(1+t)^{-\frac{3}{2}(1-\frac{1}{p})}$ . This follows from the estimates in references [1], since  $v_1$  and  $v_2$  belong to  $C([0, +\infty); L^p)$ . However, theorem A guarantees that  $v_2$  exists (in the above space), and that the constants  $C$  and  $y_0$  depend only on the unperturbed solution  $v_1$ .

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Department of Mathematics  
University of Trento

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